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**DEFENCE SCIENCE AND TECHNOLOGY ORGANISATION**  
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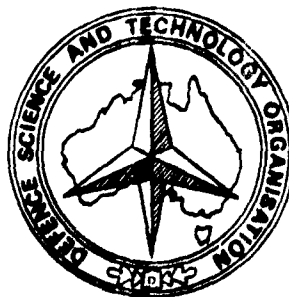
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**WIND TUNNEL TESTS ON THE STATIC AERODYNAMICS OF  
A SPINNING 106 MM ARTILLERY SHELL MODEL**

C. JERNEY

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9 TECHNICAL REPORT  
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6 WIND TUNNEL TESTS ON THE STATIC AERODYNAMICS OF A  
SPINNING 105 MM ARTILLERY SHELL MODEL.

10 C. Jerney

12 47 p.

#### S U M M A R Y

The aerodynamic characteristics of a spinning 105 mm shell shape have been measured as a prelude to tests of a shell shape fitted with canard control surfaces. Tests were conducted at incidences of zero to  $15^{\circ}$ , and Mach numbers of 0.70 to 0.95 and 1.4. Results indicate that the use of canard surfaces to control the flight path of such a projectile is unlikely to be very effective within the low transonic Mach number range, but could possibly be effective in supersonic flight.

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↙ The aerodynamic characteristics of a spinning 105 mm shell shape have been measured as a prelude to tests of a shell shape fitted with canard control surfaces. Tests were conducted at incidences of zero to  $15^{\circ}$ , and Mach numbers of 0.70 to 0.95 and 1.4. Results indicate that the use of canard surfaces to control the flight path of such a projectile is unlikely to be very effective within the low transonic Mach number range, but could possibly be effective in supersonic flight. ↗

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10. Variation of  $C_{Z_u}$ ,  $C_{m_u}$ ,  $C_{Y_{p\alpha}}$  and  $C_{n_{p\alpha}}$  with Mach no. and roll rate, at  $\alpha = 0^\circ$

## 1. INTRODUCTION

The work reported here was conducted as a preliminary step in a program to assess the feasibility of using canard controls on a spinning projectile to control its flight path, and hence its point of impact. The projectile shape chosen was the 105 mm H.E. M1 shell with M557 P.D. fuse and the tests were designed to provide a data bank for comparison with later tests of a canard equipped shell shape. The test programme also provided the opportunity to develop the equipment and techniques needed for this type of work.

The basic equipment for the wind tunnel testing of rapidly spinning models already existed as a result of a Magnus research project some years earlier, and this equipment was modified as necessary to accommodate the new model and new data requirements. The tests were carried out during September and November of 1977, and since no significant problems occurred, considerable confidence was gained in the equipment and techniques used.

## 2. EXPERIMENTAL DETAILS

### 2.1 Model and balance

The model used was a half scale model of the 105 mm H.E. M1 shell, fitted with an M557 P.D. fuse. Production drawings were used for all dimensions, except for details of the drive band, which were obtained by direct measurement from a fired shell.

Figures 1 and 2 show the model and the balance assembled, figure 1 showing the internal details of the drive and roll rate measuring system. In figure 2 it may be seen that the direction of the rifling grooves on the drive band is opposite to that on the full size shell. This is because the roll drive motor operates only in the opposite sense to the rotation of the full size shell. Consequently, all roll rates in this report are negative and Magnus forces and moments are of opposite sign to those existing on the full size shell.

The model was mounted onto the shaft of a sliding-vane type air motor, which incorporates an air-bearing for low friction radial support, and this then fitted onto the end of a strain gauge sting balance. The high pressure air for the motor was supplied through the hollow core of the balance, and the low pressure air for the air-bearing through two thin tubes taped to the outside of the sting. The roll rate of the model was monitored by a "hall effect" sensor, mounted on the sting and triggered once each revolution by a small magnet on the model. Control of the roll rate was effected by varying the pressure of the air supply to the motor.

Since spin rates of up to 330 r/s were required, careful dynamic balancing of the model was necessary before commencing wind tunnel testing. This was accomplished outside the tunnel with the model mounted on the strain gauge balance and the balance outputs monitored on a CRO screen. Observation of the amplitude and phase of the outputs as the model was spun enabled the positioning of small masses on the outside of the model to compensate for the imbalance observed. These balancing masses were then translated into internal masses, which were fitted, and then the model spun again as a check. Excellent balance was obtained, with only one fairly "noisy" resonant area at about 125 r/s, corresponding to oscillation about the front cage of the balance. This spin rate was therefore avoided where possible during the wind tunnel tests.

### 2.2 Experimental procedure

All tests reported here were carried out in the 360 mm x 380 mm slotted working section of the continuous flow wind tunnel S-1 at the Aeroballistics Division of WSRL. Data were obtained for the subsonic Mach number range of 0.70 to 0.95 and also at a Mach number of 1.4.



A Reynolds number of  $R_d = 3.9 \times 10^5$  (based on maximum body diameter) was used throughout the tests, this being the highest Reynolds number attainable for the complete range of Mach numbers without overloading the balance. This compares with flight Reynolds numbers which are typically  $1.0$  to  $2.0 \times 10^6$ . A boundary layer trip, shown and described in figure 1, was included to ensure a turbulent boundary layer over the shell body, to simulate flow conditions expected at the higher Reynolds numbers of the full scale shell.

The experimental procedure consisted of establishing the required tunnel flow conditions, setting the required model roll rate by adjusting the motor supply pressure, and then conducting a pitch traverse of the model from  $-4^\circ$  to  $15^\circ$ , taking data at one degree intervals. For the tests at zero roll rate it was found necessary to shut off the air supply to the model air bearing, otherwise the torque generated by the grooves of the driving band was sufficient to produce a small steady roll rate. With no air supplied, the friction between the air bearing surfaces prevented the model from rolling. For consistency, all non-rolling tests were conducted at a constant roll orientation, chosen to be with the fuse delay adjustment screw hole on the windward streamline. Brief tests at other roll orientations, however, showed no discernible differences in the measured forces and moments.

### 2.3 Accuracy of results

The results consist of aerodynamic force and moment coefficients at given Mach numbers, Reynolds number, incidences and roll rates. The sources of error and the accuracy applicable to each item are discussed below.

#### (a) Force and moment coefficients

These were obtained from the electrical outputs of the strain gauges on the sting balance. The major sources of error are in the balance calibration and the dynamic effects of the spinning model, i.e., vibration and the discharge of exhaust air. Under static conditions the balance is capable of measuring forces and moments to an accuracy of 0.1%. No attempt was made to calibrate the balance under dynamic conditions, but comparison of spinning and non-spinning tests with no tunnel flow indicated that discrepancies were small, generally less than 0.5%. A reasonable estimate of the maximum percentage uncertainty in the force and moment coefficients would therefore be 1%.

An absolute uncertainty also exists in each force and moment coefficient, arising mainly from the resolution limits of the measuring system, balance temperature changes, and noise levels in the balance outputs. This uncertainty is variable with Mach number and incidence, but is of a maximum order of 0.01 for all coefficients.

#### (b) Mach numbers

The Mach number is manually controlled from observation of the stagnation pressure in the settling chamber and the static pressure in the working section. Mach numbers are held to within 0.01 of the nominal figure, and this is also the level of spatial uncertainty in the centreline Mach number of the working section. No corrections have been applied for the effects of blockage.

#### (c) Reynolds number

The Reynolds number is derived from the Mach number and stagnation temperature of the air flow, and since the stagnation temperature varies somewhat during a tunnel run, the Reynolds number varies correspondingly. For all tests reported here the Reynolds number was within the range  $(3.9 \pm 0.1) \times 10^5$ .

## (d) Incidence

The combined effect of errors in support attitude measurement and sting bending corrections produces an uncertainty in attitude measurement of less than  $0.01^\circ$ . However, airflow direction on the tunnel axis is uniform only to within  $0.2^\circ$ , so that this is a more realistic estimate of the uncertainty in the incidences quoted.

## (e) Roll rate

Roll rates were obtained by using a counter to display the total number of pulses received each second from the model, which generated one pulse per revolution. All data were taken only after the model had reached a steady roll rate, although small changes inevitably occurred as the incidence was varied during a run. The roll rate given for each data point is therefore accurate to within 1 r/s (6 rad/s), but the approximate roll rates for an entire run may have uncertainties of up to 3 r/s (19 rad/s).

## 3. PRESENTATION AND DISCUSSION OF RESULTS

## 3.1 Presentation of results

Results are presented in tabular form as Tables 1 to 7, and also in graphical form as figures 4 to 10, where selected results have been plotted to illustrate trends as a function of incidence, Mach number and roll rate. Figure 3 shows the axis system used throughout, the origin of the system being positioned at the nominal centre of gravity of the shell, i.e., 2.97 calibers from the nose tip.

The tabular data are presented as 'raw' computer output, and so must be interpreted with some care. In particular, centres of pressure are derived from the division of a moment coefficient by a force coefficient, and so are subject to large errors as the force approaches zero.

Figures 4 and 5 show that normal force and pitching moment are continuous functions of incidence up to  $15^\circ$  for all Mach numbers, indicating that no sudden changes occur in the cross-flow pattern within this range. Also of interest is that spin rate has very little effect on the normal force and pitching moment. This is further illustrated in figure 6, where normal force and pitching moment are plotted against non-dimensional spin rate

( $p' = \frac{p d}{2 U_\infty}$ ) for various Mach numbers and incidences (typical flight values of non-dimensional spin rate are within the range 0.14 to 0.20). The centre of pressure in the pitch plane is plotted in figure 7, which shows that for subsonic conditions, increasing spin rate tends to bring the centre of pressure back from the nose, especially at lower incidences. Figure 7 also shows that the subsonic centre of pressure is well forward, generally less than one caliber from the nose, and in some cases even ahead of the nose. The centre of pressure also varies considerably with Mach number and incidence, being furthest forward for transonic and low incidence conditions. The supersonic centre of pressure is further back (approximately  $1\frac{1}{2}$  calibers from the nose) and is less variable with incidence and spin rate.

Figure 8 shows the effect of incidence, Mach number and spin rate on the side (Magnus) force coefficient. In general it shows a relatively linear increase with increasing incidence and spin rate, though with some scatter, thought to be due mainly to the difficulty of measuring the relatively small forces involved. However, at transonic conditions this linearity is lost at the higher incidences, where increasing incidence reduces the side force and may even reverse its direction.

Figure 9 shows the yawing (Magnus) moment coefficient and its variation with incidence, Mach number and roll rate. The proximity of the yaw plane centre of pressure to the origin of the axis system results in the yawing moments being very small, generally of a similar order to the level of uncertainty in their measurement (0.01). Trends are therefore largely submerged in the noise level except for high subsonic conditions (Mach 0.9 and 0.95) where the non-linearity of the Magnus effects with incidence is again evident.

Figure 10 shows the variation of the force and moment coefficient derivatives with Mach number (at zero incidence). Generally speaking, they show the tendency of relatively gradual change at moderate subsonic speeds, more rapid change at transonic speeds leading to extreme values, and a return to more moderate values at supersonic speed. As has already been noted, the aerodynamic characteristics of the shell shape are significantly non-linear at high incidence, and so the derivatives given in figure 10 are valid only at low incidence, i.e., less than  $5^\circ$ .

### 3.2 Implications for the use of canard controls

Results indicate that the use of canard surfaces to control the attitude and hence the flight path of a 105 mm shell is unlikely to be very effective within the transonic Mach number range. This is because the centre of pressure in the pitch plane is situated very close to the likely canard position, and is highly variable with variations in Mach number, incidence and spin rate. The canard normal force required to produce trim at incidence will therefore be almost equal and opposite to the body normal force, and so the resultant normal force at trim is likely to be small and highly variable with Mach number, incidence and spin rate. Side (Magnus) forces are also small and are non-linear at high incidence and high Mach number.

Canard controls could possibly be effective in supersonic flight since the centre of pressure is then further back along the body and much less sensitive to variations in incidence and spin rate.

# NOTATION

$C_Z$	normal force coefficient = $\frac{Z}{qS}$
$C_Y$	side force coefficient = $\frac{Y}{qS}$
$C_m$	pitching moment coefficient = $\frac{m}{qSd}$
$C_n$	yawing moment coefficient = $\frac{n}{qSd}$
$C.P._z$	position of centre of pressure in the pitch plane, forward of cg is +ve
$C.P._y$	position of centre of pressure in the yaw plane, forward of cg is +ve
$C_{Z_u}$	derivative of normal force coefficient with respect to incidence = $\partial C_Z / \partial \alpha$
$C_{m_\alpha}$	derivative of pitching moment coefficient with respect to incidence = $\partial C_m / \partial \alpha$
$C_{Y_{p\alpha}}$	double derivative of side force coefficient with respect to roll rate and incidence = $\partial^2 C_Y / \partial p' \partial \alpha$
$C_{n_{p\alpha}}$	double derivative of yawing moment coefficient with respect to roll rate and incidence = $\partial^2 C_n / \partial p' \partial \alpha$
$M$	Mach number of free stream
$R_d$	Reynolds number of free stream, based on maximum body diameter
$S$	maximum body cross sectional area
$U_\infty$	velocity of free stream
$Y$	side force
$Z$	normal force
$d$	maximum body diameter
$m$	pitching moment
$n$	yawing moment
$p$	roll rate; clockwise from rear is +ve
$p'$	non-dimensional roll rate = $\frac{pd}{2 U_\infty}$
$q$	dynamic pressure of free stream
$\alpha$	incidence angle relative to free stream

TABLE 1. AERODYNAMIC COEFFICIENTS,  $M = 0.70$ 

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.93	2.573	0.003	0.102	-0.263	-0.001	-0.41	0.-0.0000	
-2.92	2.605	0.003	0.073	-0.191	-0.001	-0.31	0.-0.0000	
-1.92	2.671	0.002	0.045	-0.120	-0.000	-0.12	0.-0.0000	
-0.92	2.608	0.002	0.018	-0.048	0.000	0.14	0.-0.0000	
0.09	2.456	0.002	-0.011	0.026	0.001	0.57	0.-0.0000	
1.09	2.521	0.002	-0.039	0.098	0.001	0.84	0.-0.0000	
2.11	2.546	0.001	-0.038	0.172	0.002	1.48	0.-0.0000	
3.11	2.563	0.001	-0.095	0.242	0.002	1.84	0.-0.0000	
4.10	2.523	0.001	-0.125	0.314	0.002	2.43	0.-0.0000	
5.11	2.466	0.001	-0.156	0.384	0.003	3.75	0.-0.0000	
6.15	2.424	0.001	-0.187	0.455	0.003	5.69	0.-0.0000	
7.13	2.394	0.000	-0.219	0.524	0.003	7.96	0.-0.0000	
8.15	2.350	0.000	-0.253	0.594	0.004	17.71	0.-0.0000	
9.15	2.300	0.000	-0.287	0.661	0.004	54.10	0.-0.0000	
10.15	2.253	-0.000	-0.322	0.726	0.004	-14.64	0.-0.0000	
11.17	2.192	0.000	-0.362	0.793	0.005	26.33	0.-0.0000	
12.17	2.132	-0.000	-0.402	0.856	0.004	-7.85	0.-0.0000	
13.19	2.066	-0.000	-0.445	0.919	0.003	-7.67	0.-0.0000	
14.21	1.991	-0.001	-0.492	0.979	0.003	-2.17	0.-0.0000	
15.19	1.919	-0.003	-0.539	1.034	0.004	-1.22	0.-0.0000	

(a)  $p = 0$ 

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.92	2.644	-0.006	0.100	-0.265	0.015	-2.73	-942.-0.1029	
-2.91	2.760	-0.011	0.070	-0.192	0.009	-0.83	-936.-0.1022	
-1.90	2.826	-0.005	0.043	-0.121	0.011	-2.37	-942.-0.1029	
-0.89	3.173	-0.003	0.015	-0.048	0.010	-2.89	-936.-0.1022	
0.10	1.786	0.001	-0.013	0.023	0.011	12.88	-936.-0.1022	
1.12	2.339	0.002	-0.042	0.099	0.009	5.49	-936.-0.1020	
2.13	2.456	0.008	-0.070	0.172	0.011	1.42	-936.-0.1020	
3.14	2.488	0.010	-0.097	0.242	0.010	0.98	-930.-0.1015	
4.15	2.454	0.012	-0.127	0.312	0.008	0.71	-930.-0.1013	
5.15	2.412	0.014	-0.158	0.381	0.008	0.55	-936.-0.1020	
6.17	2.373	0.015	-0.191	0.452	0.005	0.36	-936.-0.1020	
7.18	2.334	0.017	-0.224	0.522	0.003	0.18	-936.-0.1020	
8.18	2.291	0.024	-0.257	0.589	0.005	0.22	-949.-0.1034	
9.19	2.254	0.026	-0.292	0.657	0.001	0.05	-942.-0.1027	
10.20	2.202	0.027	-0.327	0.721	0.000	0.01	-949.-0.1034	
11.21	2.161	0.032	-0.364	0.787	0.005	0.16	-949.-0.1034	
12.22	2.106	0.032	-0.404	0.851	0.007	0.22	-955.-0.1041	
13.22	2.035	0.033	-0.448	0.912	0.006	0.20	-955.-0.1041	
14.24	1.964	0.039	-0.495	0.971	0.010	0.25	-955.-0.1041	
15.24	1.891	0.035	-0.544	1.030	0.007	0.19	-955.-0.1041	

(b)  $p \approx -150$  rev/s

TABLE 1(CONTD.).

$a^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.92	2.832	-0.015	0.093	-0.264	0.017	-1.15-1565.-	-0.1705	
-2.91	2.935	-0.006	0.066	-0.194	0.019	-2.35-1565.-	-0.1705	
-1.90	3.179	-0.006	0.038	-0.121	0.017	-2.82-1571.-	-0.1712	
-0.89	5.097	-0.004	0.010	-0.049	0.013	-3.35-1571.-	-0.1712	
0.10	1.280	-0.001	-0.017	0.022	0.012	-17.56-1565.-	-0.1705	
1.12	2.090	-0.000	-0.045	0.094	0.009	-22.75-1565.-	-0.1705	
2.13	2.270	0.005	-0.074	0.168	0.008	1.52-1565.-	-0.1705	
3.15	2.347	0.011	-0.102	0.240	0.008	0.73-1565.-	-0.1705	
4.15	2.377	0.015	-0.131	0.311	0.004	0.28-1565.-	-0.1705	
5.15	2.373	0.021	-0.161	0.382	0.004	0.21-1558.-	-0.1698	
6.17	2.311	0.029	-0.196	0.453	0.005	0.16-1558.-	-0.1698	
7.18	2.274	0.036	-0.229	0.520	0.004	0.12-1558.-	-0.1698	
8.18	2.223	0.034	-0.263	0.584	-0.002	-0.06-1565.-	-0.1705	
9.19	2.184	0.046	-0.299	0.653	0.003	0.07-1565.-	-0.1705	
10.20	2.134	0.044	-0.336	0.717	-0.003	-0.06-1565.-	-0.1705	
11.21	2.082	0.051	-0.376	0.783	-0.000	-0.01-1558.-	-0.1698	
12.22	2.043	0.055	-0.414	0.846	-0.004	-0.06-1565.-	-0.1702	
13.22	1.974	0.060	-0.458	0.904	0.003	0.05-1565.-	-0.1702	
14.24	1.907	0.063	-0.504	0.961	0.005	0.08-1565.-	-0.1702	
15.24	1.838	0.067	-0.555	1.021	0.008	0.11-1565.-	-0.1705	

(c)  $p \approx -249$  rev/s

TABLE 2. AERODYNAMIC COEFFICIENTS,  $M = 0.75$ 

$\alpha^\circ$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.95	2.592	0.002	0.103	-0.268	-0.001	-0.32	0.-0.0000	
-2.95	2.616	0.002	0.076	-0.197	-0.000	-0.01	0.-0.0000	
-1.93	2.640	0.002	0.046	-0.123	0.001	0.41	0.-0.0000	
-0.93	2.594	0.001	0.019	-0.049	0.001	1.02	0.-0.0000	
0.07	2.717	0.001	-0.009	0.024	0.002	2.07	0.-0.0000	
1.08	2.670	0.001	-0.037	0.099	0.003	3.57	0.-0.0000	
2.10	2.659	0.000	-0.065	0.173	0.003	7.99	0.-0.0000	
3.12	2.637	0.000	-0.093	0.245	0.003	8.05	0.-0.0000	
4.09	2.601	-0.000	-0.120	0.313	0.004	-16.36	0.-0.0000	
5.11	2.539	-0.000	-0.153	0.388	0.004	-13.09	0.-0.0000	
6.13	2.496	-0.000	-0.184	0.458	0.004	-12.40	0.-0.0000	
7.13	2.443	-0.001	-0.216	0.528	0.005	-8.76	0.-0.0000	
8.15	2.395	-0.001	-0.250	0.598	0.005	-6.89	0.-0.0000	
9.15	2.345	-0.001	-0.284	0.665	0.005	-5.51	0.-0.0000	
10.15	2.291	-0.002	-0.320	0.733	0.006	-3.70	0.-0.0000	
11.18	2.225	-0.001	-0.359	0.799	0.006	-6.30	0.-0.0000	
12.18	2.162	-0.002	-0.399	0.862	0.005	-3.08	0.-0.0000	
13.18	2.092	-0.003	-0.443	0.927	0.003	-1.13	0.-0.0000	
14.20	2.015	-0.001	-0.489	0.985	0.004	-5.95	0.-0.0000	
15.21	1.938	-0.002	-0.540	1.047	0.005	-2.14	0.-0.0000	

(a)  $p = 0$ 

$\alpha^\circ$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.95	2.636	-0.005	0.103	-0.271	0.013	-2.46	-936.-0.0960	
-2.95	2.699	-0.008	0.074	-0.200	0.008	-0.95	-942.-0.0966	
-1.93	2.831	-0.002	0.045	-0.126	0.011	-6.42	-942.-0.0966	
-0.93	3.051	-0.002	0.018	-0.055	0.010	-6.32	-942.-0.0966	
0.07	1.706	-0.001	-0.011	0.019	0.007	-5.96	-949.-0.0973	
1.08	2.357	0.000	-0.040	0.094	0.006	104.11	-949.-0.0973	
2.10	2.455	0.005	-0.068	0.168	0.008	1.45	-942.-0.0966	
3.13	2.460	0.005	-0.099	0.243	0.004	0.86	-955.-0.0979	
4.11	2.441	0.011	-0.127	0.311	0.006	0.50	-961.-0.0986	
5.13	2.329	0.014	-0.160	0.382	0.004	0.31	-955.-0.0979	
6.13	2.360	0.015	-0.192	0.454	0.004	0.26	-949.-0.0973	
7.14	2.327	0.020	-0.226	0.525	0.001	0.05	-955.-0.0979	
8.15	2.286	0.020	-0.259	0.592	-0.002	-0.09	-949.-0.0973	
9.17	2.256	0.028	-0.294	0.664	0.001	0.03	-949.-0.0973	
10.16	2.218	0.030	-0.329	0.730	0.001	0.04	-949.-0.0973	
11.18	2.166	0.033	-0.367	0.795	0.004	0.12	-949.-0.0973	
12.19	2.112	0.033	-0.406	0.857	0.006	0.17	-949.-0.0973	
13.20	2.048	0.033	-0.450	0.921	0.005	0.14	-955.-0.0979	
14.21	1.979	0.037	-0.497	0.984	0.007	0.20	-955.-0.0979	
15.21	1.906	0.039	-0.546	1.041	0.008	0.21	-955.-0.0979	

(b)  $p \approx -151$  rev/s

TABLE 2(CONTD.).

$\alpha^0$	C.P. <sub>z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.95	2.815	-0.012	0.096	-0.271	0.016	-1.35-1571.	-0.1611	
-2.94	2.974	-0.012	0.068	-0.201	0.012	-0.94-1571.	-0.1611	
-1.94	3.218	-0.006	0.040	-0.128	0.012	-2.23-1571.	-0.1611	
-0.93	4.158	-0.001	0.013	-0.055	0.013	-20.02-1565.	-0.1604	
0.08	1.261	0.001	-0.015	0.018	0.010	12.65-1571.	-0.1611	
1.08	2.179	0.004	-0.042	0.093	0.008	2.18-1565.	-0.1604	
2.09	2.364	0.009	-0.070	0.167	0.007	0.85-1565.	-0.1604	
3.11	2.432	0.013	-0.099	0.240	0.005	0.39-1565.	-0.1604	
4.11	2.432	0.015	-0.128	0.311	0.002	0.12-1565.	-0.1604	
5.12	2.395	0.020	-0.160	0.383	-0.001	-0.05-1565.	-0.1604	
6.14	2.352	0.028	-0.193	0.454	0.001	0.04-1565.	-0.1604	
7.15	2.309	0.030	-0.226	0.522	-0.002	-0.07-1565.	-0.1604	
8.16	2.258	0.033	-0.263	0.594	-0.006	-0.18-1565.	-0.1604	
9.16	2.217	0.046	-0.297	0.659	-0.001	-0.02-1565.	-0.1604	
10.16	2.161	0.045	-0.337	0.728	-0.006	-0.14-1565.	-0.1604	
11.19	2.116	0.055	-0.374	0.792	-0.001	-0.01-1565.	-0.1604	
12.19	2.068	0.056	-0.413	0.855	-0.001	-0.01-1558.	-0.1598	
13.20	1.997	0.059	-0.460	0.919	0.001	0.02-1565.	-0.1604	
14.22	1.929	0.060	-0.506	0.977	0.000	0.01-1565.	-0.1604	
15.20	1.867	0.064	-0.555	1.036	0.003	0.05-1565.	-0.1604	

(c)  $p \approx -249$  rev/s



TABLE 3. AERODYNAMIC COEFFICIENTS,  $M = 0.80$ 

$\alpha^\circ$	C.P. <sub>Z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.96	2.683	0.002	0.104	-0.278	-0.001	-0.27	0.-0.0000	
-2.96	2.722	0.002	0.075	-0.204	0.000	0.09	0.-0.0000	
-1.94	2.760	0.002	0.045	-0.125	0.001	0.68	0.-0.0000	
-0.94	2.714	0.001	0.019	-0.051	0.002	1.44	0.-0.0000	
0.06	3.414	0.000	-0.007	0.023	0.002	6.91	0.-0.0000	
1.08	2.810	0.000	-0.036	0.100	0.003	11.20	0.-0.0000	
2.08	2.788	-0.000	-0.063	0.177	0.003	-177.66	0.-0.0000	
3.11	2.720	-0.000	-0.092	0.250	0.004	-10.21	0.-0.0000	
4.10	2.682	-0.001	-0.120	0.323	0.004	-5.91	0.-0.0000	
5.11	2.618	-0.001	-0.152	0.398	0.004	-4.39	0.-0.0000	
6.13	2.564	-0.001	-0.183	0.470	0.004	-5.06	0.-0.0000	
7.13	2.510	-0.001	-0.215	0.540	0.004	-4.80	0.-0.0000	
8.15	2.463	-0.001	-0.249	0.614	0.004	-3.66	0.-0.0000	
9.17	2.402	-0.001	-0.285	0.684	0.005	-3.82	0.-0.0000	
10.16	2.334	-0.002	-0.320	0.747	0.005	-2.75	0.-0.0000	
11.18	2.268	-0.001	-0.360	0.816	0.005	-4.46	0.-0.0000	
12.18	2.196	-0.002	-0.400	0.878	0.004	-2.84	0.-0.0000	
13.20	2.121	-0.003	-0.445	0.944	0.004	-1.39	0.-0.0000	
14.21	2.047	-0.000	-0.492	1.006	0.003	-10.29	0.-0.0000	
15.22	1.961	-0.002	-0.543	1.066	0.004	-1.56	0.-0.0000	

(a)  $p = 0$ 

$\alpha^\circ$	C.P. <sub>Z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.95	2.767	-0.006	0.101	-0.279	0.012	-1.84	-999.-0.0970	
-2.95	2.845	-0.004	0.072	-0.205	0.012	-3.41	-930.-0.0903	
-1.94	2.875	-0.003	0.045	-0.131	0.011	-3.78	-930.-0.0903	
-0.94	3.255	0.002	0.017	-0.055	0.013	6.14	-930.-0.0903	
0.07	1.924	0.003	-0.012	0.023	0.011	4.23	-930.-0.0903	
1.10	2.486	0.003	-0.040	0.099	0.009	2.75	-930.-0.0903	
2.10	2.586	0.005	-0.068	0.175	0.008	1.52	-930.-0.0903	
3.12	2.578	0.005	-0.097	0.251	0.004	0.91	-930.-0.0903	
4.11	2.539	0.010	-0.126	0.319	0.006	0.63	-930.-0.0903	
5.12	2.485	0.016	-0.158	0.393	0.008	0.48	-930.-0.0903	
6.14	2.437	0.015	-0.191	0.466	0.004	0.27	-924.-0.0897	
7.14	2.410	0.023	-0.223	0.537	0.005	0.21	-924.-0.0897	
8.16	2.359	0.023	-0.257	0.607	0.001	0.03	-924.-0.0897	
9.16	2.305	0.026	-0.295	0.679	-0.000	-0.01	-930.-0.0903	
10.16	2.261	0.029	-0.331	0.748	0.001	0.02	-924.-0.0897	
11.18	2.206	0.031	-0.369	0.815	0.004	0.12	-930.-0.0903	
12.19	2.153	0.032	-0.409	0.880	0.006	0.20	-936.-0.0909	
13.22	2.088	0.032	-0.453	0.947	0.008	0.25	-930.-0.0902	
14.21	2.013	0.032	-0.500	1.007	0.007	0.24	-936.-0.0909	
15.21	1.933	0.034	-0.554	1.070	0.009	0.26	-942.-0.0914	

(b)  $p \approx -148$  rev/s

TABLE 3(CONTD.).

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.95	2.957	-0.009	0.095	-0.281	0.018	-1.93-1508.	-0.1462	
-2.95	3.068	-0.010	0.068	-0.208	0.014	-1.42-1508.	-0.1460	
-1.95	3.277	-0.006	0.041	-0.134	0.014	-2.45-1502.	-0.1454	
-0.93	4.398	-0.004	0.013	-0.058	0.012	-3.11-1502.	-0.1456	
0.06	1.302	-0.000	-0.014	0.018	0.010	-23.85-1502.	-0.1456	
1.08	2.294	0.005	-0.042	0.096	0.010	2.18-1508.	-0.1460	
2.11	2.435	0.005	-0.072	0.176	0.006	1.16-1502.	-0.1456	
3.11	2.533	0.009	-0.098	0.249	0.004	0.46-1502.	-0.1456	
4.10	2.504	0.017	-0.128	0.321	0.005	0.30-1502.	-0.1456	
5.12	2.488	0.021	-0.159	0.395	0.002	0.11-1502.	-0.1454	
6.15	2.433	0.023	-0.192	0.467	-0.002	-0.07-1502.	-0.1454	
7.13	2.376	0.030	-0.226	0.537	0.000	0.00-1508.	-0.1462	
8.16	2.320	0.036	-0.262	0.608	-0.002	-0.05-1502.	-0.1454	
9.16	2.272	0.038	-0.298	0.676	-0.004	-0.10-1502.	-0.1454	
10.17	2.219	0.044	-0.337	0.747	-0.003	-0.06-1514.	-0.1466	
11.19	2.167	0.048	-0.376	0.814	-0.000	-0.00-1508.	-0.1460	
12.18	2.120	0.051	-0.413	0.876	0.002	0.03-1514.	-0.1466	
13.22	2.043	0.052	-0.461	0.942	0.002	0.03-1508.	-0.1460	
14.21	1.975	0.053	-0.509	1.006	0.002	0.03-1514.	-0.1466	
15.21	1.897	0.056	-0.561	1.065	0.004	0.07-1508.	-0.1460	

(c)  $p \approx -240$  rev/s

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.95	3.058	-0.018	0.094	-0.286	0.018	-1.00-1967.	-0.1904	
-2.96	3.249	-0.013	0.065	-0.212	0.016	-1.17-1960.	-0.1898	
-1.94	3.711	-0.007	0.037	-0.137	0.015	-2.11-1960.	-0.1898	
-0.94	6.293	-0.004	0.010	-0.061	0.011	-2.64-1960.	-0.1898	
0.07	0.918	-0.002	-0.017	0.016	0.008	-4.08-1960.	-0.1898	
1.08	2.086	0.010	-0.045	0.093	0.011	1.15-1960.	-0.1898	
2.11	2.316	0.009	-0.073	0.169	0.005	0.57-1960.	-0.1898	
3.11	2.394	0.017	-0.102	0.243	0.005	0.33-1960.	-0.1898	
4.10	2.438	0.020	-0.130	0.317	0.002	0.09-1954.	-0.1892	
5.12	2.426	0.028	-0.162	0.394	0.000	0.02-1954.	-0.1889	
6.15	2.396	0.033	-0.195	0.468	-0.002	-0.07-1954.	-0.1889	
7.14	2.344	0.037	-0.228	0.535	-0.006	-0.15-1954.	-0.1889	
8.16	2.283	0.044	-0.266	0.606	-0.006	-0.13-1954.	-0.1892	
9.16	2.212	0.051	-0.305	0.675	-0.007	-0.14-1954.	-0.1892	
10.17	2.154	0.055	-0.345	0.744	-0.009	-0.17-1960.	-0.1898	
11.19	2.105	0.061	-0.386	0.812	-0.007	-0.11-1960.	-0.1898	
12.19	2.052	0.068	-0.428	0.879	-0.003	-0.05-1954.	-0.1889	
13.20	1.997	0.071	-0.470	0.938	0.000	0.00-1960.	-0.1895	
14.22	1.925	0.072	-0.519	1.000	-0.000	-0.00-1960.	-0.1895	
15.21	1.859	0.075	-0.571	1.061	0.003	0.04-1967.	-0.1904	

(d)  $p \approx -312$  rev/s

TABLE 4. AERODYNAMIC COEFFICIENTS,  $M = 0.85$ 

$\alpha^0$	C.P. <sub>Z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.98	2.771	0.003	0.103	-0.286	-0.001	-0.45	0.-0.0000	
-2.97	2.832	0.003	0.074	-0.211	-0.001	-0.30	0.-0.0000	
-1.95	2.887	0.002	0.046	-0.134	0.000	0.11	0.-0.0000	
-0.92	2.911	0.001	0.018	-0.054	0.001	0.48	0.-0.0000	
0.07	3.049	0.001	-0.008	0.025	0.001	1.39	0.-0.0000	
1.07	2.984	0.001	-0.034	0.102	0.002	2.32	0.-0.0000	
2.11	2.890	0.000	-0.062	0.180	0.002	4.51	0.-0.0000	
3.12	2.838	0.000	-0.091	0.257	0.002	26.21	0.-0.0000	
4.10	2.781	-0.000	-0.119	0.332	0.003	-9.56	0.-0.0000	
5.11	2.721	-0.001	-0.149	0.406	0.003	-5.25	0.-0.0000	
6.13	2.681	-0.001	-0.181	0.480	0.003	-5.75	0.-0.0000	
7.14	2.607	-0.001	-0.212	0.553	0.004	-4.60	0.-0.0000	
8.16	2.552	-0.001	-0.246	0.628	0.004	-3.26	0.-0.0000	
9.16	2.488	-0.001	-0.282	0.701	0.004	-3.43	0.-0.0000	
10.16	2.415	-0.002	-0.320	0.773	0.004	-2.57	0.-0.0000	
11.19	2.336	-0.001	-0.361	0.844	0.004	-4.85	0.-0.0000	
12.19	2.261	-0.001	-0.404	0.913	0.005	-4.52	0.-0.0000	
13.20	2.172	-0.002	-0.445	0.966	0.004	-1.81	0.-0.0000	
14.22	2.086	-0.001	-0.493	1.028	0.002	-3.87	0.-0.0000	
15.23	1.996	-0.003	-0.548	1.094	0.002	-0.70	0.-0.0000	

(a)  $p = 0$ 

$\alpha^0$	C.P. <sub>Z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.96	2.911	-0.010	0.099	-0.287	0.008	-0.84	-942.-0.0868	
-2.95	3.002	-0.004	0.071	-0.213	0.012	-2.63	-949.-0.0873	
-1.94	3.101	-0.004	0.044	-0.137	0.009	-2.16	-949.-0.0873	
-0.94	3.479	0.000	0.017	-0.059	0.010	27.47	-949.-0.0873	
0.07	1.901	0.002	-0.011	0.020	0.009	5.63	-949.-0.0873	
1.09	2.613	0.004	-0.039	0.101	0.009	2.08	-949.-0.0873	
2.09	2.695	0.006	-0.066	0.177	0.008	1.21	-949.-0.0873	
3.11	2.699	0.006	-0.095	0.256	0.004	0.65	-942.-0.0868	
4.10	2.633	0.010	-0.125	0.330	0.003	0.32	-942.-0.0868	
5.13	2.615	0.014	-0.156	0.409	0.003	0.20	-942.-0.0868	
6.14	2.574	0.015	-0.189	0.486	0.001	0.04	-942.-0.0868	
7.15	2.503	0.022	-0.220	0.551	0.001	0.02	-949.-0.0873	
8.16	2.451	0.024	-0.255	0.625	-0.003	-0.11	-949.-0.0873	
9.16	2.401	0.025	-0.291	0.700	-0.004	-0.18	-942.-0.0868	
10.18	2.347	0.029	-0.328	0.770	-0.002	-0.06	-949.-0.0873	
11.20	2.279	0.031	-0.369	0.841	0.002	0.05	-949.-0.0872	
12.20	2.211	0.031	-0.410	0.906	0.005	0.17	-949.-0.0873	
13.23	2.140	0.027	-0.456	0.975	0.006	0.20	-955.-0.0879	
14.22	2.066	0.033	-0.503	1.039	0.008	0.26	-955.-0.0878	
15.22	1.975	0.032	-0.556	1.099	0.006	0.19	-955.-0.0879	

(b)  $p \approx -151$  rev/s

TABLE 4(CONTD.).

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.97	3.060	-0.010	0.096	-0.293	0.017	-1.63-1495.	-0.1375	
-2.96	3.219	-0.006	0.068	-0.218	0.017	-2.68-1489.	-0.1369	
-1.94	3.442	-0.007	0.040	-0.139	0.013	-1.94-1489.	-0.1369	
-0.94	4.246	-0.003	0.014	-0.060	0.011	-3.51-1489.	-0.1369	
0.06	1.368	0.001	-0.013	0.017	0.011	9.93-1483.	-0.1363	
1.08	2.346	0.004	-0.042	0.098	0.008	2.13-1483.	-0.1363	
2.10	2.584	0.007	-0.068	0.177	0.006	0.82-1483.	-0.1363	
3.11	2.638	0.012	-0.095	0.251	0.005	0.41-1477.	-0.1357	
4.11	2.645	0.017	-0.124	0.329	0.003	0.19-1477.	-0.1357	
5.12	2.591	0.020	-0.157	0.406	-0.001	-0.04-1477.	-0.1357	
6.14	2.532	0.027	-0.190	0.482	-0.001	-0.04-1477.	-0.1357	
7.15	2.497	0.032	-0.223	0.556	-0.003	-0.09-1477.	-0.1357	
8.18	2.407	0.035	-0.260	0.627	-0.006	-0.17-1477.	-0.1357	
9.17	2.362	0.040	-0.295	0.698	-0.006	-0.16-1477.	-0.1357	
10.17	2.305	0.044	-0.333	0.768	-0.006	-0.13-1477.	-0.1357	
11.19	2.246	0.046	-0.374	0.840	-0.003	-0.06-1477.	-0.1357	
12.19	2.187	0.050	-0.414	0.905	0.001	0.02-1477.	-0.1357	
13.22	2.115	0.050	-0.459	0.971	0.002	0.03-1477.	-0.1357	
14.22	2.032	0.054	-0.507	1.031	0.003	0.06-1477.	-0.1357	
15.22	1.951	0.055	-0.561	1.095	0.003	0.06-1483.	-0.1363	

(c)  $p \approx -236$  rev/s

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.96	3.210	-0.019	0.091	-0.294	0.018	-0.93-1948.	-0.1790	
-2.96	3.396	-0.015	0.065	-0.220	0.016	-1.03-1948.	-0.1790	
-1.94	3.858	-0.010	0.037	-0.141	0.013	-1.29-1948.	-0.1790	
-0.93	6.161	-0.003	0.010	-0.062	0.013	-4.05-1954.	-0.1796	
0.06	0.844	0.000	-0.016	0.014	0.011	27.51-1948.	-0.1790	
1.08	2.203	0.005	-0.043	0.094	0.008	1.52-1948.	-0.1790	
2.10	2.472	0.012	-0.070	0.174	0.007	0.56-1948.	-0.1790	
3.12	2.517	0.016	-0.098	0.247	0.005	0.32-1948.	-0.1790	
4.10	2.522	0.022	-0.128	0.322	0.003	0.12-1948.	-0.1790	
5.11	2.522	0.026	-0.159	0.400	-0.001	-0.04-1948.	-0.1790	
6.14	2.484	0.034	-0.191	0.475	-0.003	-0.07-1948.	-0.1790	
7.15	2.413	0.037	-0.223	0.539	-0.006	-0.15-1954.	-0.1796	
8.15	2.355	0.045	-0.260	0.611	-0.007	-0.15-1954.	-0.1796	
9.17	2.280	0.050	-0.299	0.683	-0.010	-0.20-1954.	-0.1796	
10.18	2.223	0.057	-0.339	0.753	-0.009	-0.16-1960.	-0.1802	
11.20	2.164	0.062	-0.380	0.823	-0.007	-0.12-1954.	-0.1796	
12.20	2.111	0.062	-0.420	0.886	-0.005	-0.08-1960.	-0.1802	
13.21	2.057	0.065	-0.463	0.953	-0.001	-0.02-1960.	-0.1802	
14.22	1.978	0.067	-0.512	1.012	0.001	0.01-1960.	-0.1802	
15.22	1.909	0.071	-0.564	1.076	0.003	0.04-1967.	-0.1808	

(d)  $p \approx -311$  rev/s

TABLE 5. AERODYNAMIC COEFFICIENTS,  $M = 0.90$ 

$\alpha^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.98	3.139	0.003	0.096	-0.303	-0.002	-0.65	0.-0.0000	
-2.97	3.250	0.002	0.069	-0.225	-0.001	-0.57	0.-0.0000	
-1.96	3.367	0.002	0.043	-0.144	-0.001	-0.56	0.-0.0000	
-0.92	3.366	0.001	0.017	-0.057	0.000	0.01	0.-0.0000	
0.07	3.282	0.001	-0.007	0.025	0.000	0.61	0.-0.0000	
1.08	3.320	0.000	-0.032	0.107	0.001	2.64	0.-0.0000	
2.09	3.241	0.000	-0.058	0.189	0.001	6.62	0.-0.0000	
3.10	3.100	0.000	-0.085	0.270	0.002	67.69	0.-0.0000	
4.10	3.045	-0.000	-0.114	0.346	0.003	-5.96	0.-0.0000	
5.12	2.982	-0.001	-0.143	0.426	0.003	-2.47	0.-0.0000	
6.14	2.928	-0.002	-0.173	0.506	0.003	-2.05	0.-0.0000	
7.14	2.874	-0.002	-0.204	0.587	0.004	-1.87	0.-0.0000	
8.17	2.772	-0.002	-0.238	0.660	0.005	-1.83	0.-0.0000	
9.17	2.693	-0.002	-0.274	0.738	0.005	-1.83	0.-0.0000	
10.17	2.614	-0.002	-0.311	0.814	0.004	-1.97	0.-0.0000	
11.20	2.502	-0.000	-0.352	0.882	0.004	-19.83	0.-0.0000	
12.19	2.400	-0.001	-0.396	0.950	0.003	-3.64	0.-0.0000	
13.21	2.297	-0.000	-0.444	1.019	0.002	-4.68	0.-0.0000	
14.23	2.202	0.001	-0.494	1.087	-0.000	-0.28	0.-0.0000	
15.22	2.105	0.000	-0.551	1.160	-0.001	-1.72	0.-0.0000	

(a)  $p = 0$ 

$\alpha^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.96	3.237	-0.009	0.094	-0.306	0.011	-1.18	-949.-0.0831	
-2.97	3.266	-0.007	0.068	-0.222	0.010	-1.42	-949.-0.0831	
-1.96	3.281	-0.004	0.043	-0.142	0.008	-1.90	-942.-0.0826	
-0.94	3.631	-0.002	0.016	-0.060	0.008	-3.53	-942.-0.0826	
0.06	2.426	-0.000	-0.006	0.020	0.006	-512.87	-949.-0.0831	
1.07	3.037	0.003	-0.034	0.105	0.005	1.94	-942.-0.0826	
2.08	2.977	0.005	-0.061	0.183	0.004	0.87	-949.-0.0831	
3.10	2.984	0.007	-0.088	0.263	0.003	0.34	-942.-0.0826	
4.10	2.976	0.011	-0.115	0.342	0.001	0.08	-942.-0.0826	
5.13	2.913	0.014	-0.145	0.423	-0.001	-0.10	-942.-0.0826	
6.13	2.811	0.017	-0.176	0.496	-0.003	-0.18	-949.-0.0831	
7.14	2.759	0.021	-0.208	0.575	-0.005	-0.23	-942.-0.0826	
8.15	2.680	0.025	-0.243	0.653	-0.006	-0.26	-942.-0.0826	
9.19	2.580	0.028	-0.281	0.726	-0.006	-0.22	-949.-0.0831	
10.17	2.519	0.030	-0.317	0.797	-0.005	-0.17	-955.-0.0837	
11.20	2.432	0.030	-0.357	0.869	-0.002	-0.07	-955.-0.0837	
12.20	2.338	0.030	-0.401	0.936	0.001	0.04	-955.-0.0837	
13.22	2.249	0.029	-0.447	1.005	0.004	0.14	-961.-0.0842	
14.22	2.153	0.031	-0.496	1.067	0.004	0.12	-961.-0.0842	
15.22	2.051	0.033	-0.551	1.129	0.003	0.10	-961.-0.0842	

(b)  $p \approx -151$  rev/s

TABLE 5 (CONTD.).

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.96	3.344	-0.015	0.092	-0.306	0.016	-1.03-1489.	-0.1305	
-2.96	3.422	-0.011	0.065	-0.223	0.013	-1.21-1489.	-0.1303	
-1.94	3.705	-0.007	0.039	-0.144	0.011	-1.55-1489.	-0.1305	
-0.94	4.271	-0.003	0.014	-0.061	0.009	-2.89-1483.	-0.1299	
0.06	1.700	0.000	-0.012	0.020	0.007	25.05-1483.	-0.1299	
1.08	2.752	0.004	-0.037	0.101	0.005	1.15-1483.	-0.1299	
2.08	2.870	0.008	-0.063	0.181	0.003	0.38-1489.	-0.1305	
3.11	2.928	0.013	-0.089	0.262	0.000	0.04-1483.	-0.1299	
4.11	2.871	0.017	-0.118	0.340	-0.002	-0.10-1483.	-0.1299	
5.11	2.833	0.022	-0.147	0.417	-0.005	-0.21-1489.	-0.1305	
6.13	2.787	0.028	-0.178	0.496	-0.008	-0.30-1489.	-0.1305	
7.14	2.726	0.033	-0.211	0.574	-0.011	-0.34-1489.	-0.1305	
8.15	2.640	0.039	-0.247	0.653	-0.014	-0.36-1489.	-0.1305	
9.16	2.572	0.045	-0.284	0.731	-0.015	-0.33-1489.	-0.1305	
10.17	2.467	0.046	-0.321	0.793	-0.011	-0.25-1489.	-0.1305	
11.19	2.394	0.046	-0.360	0.862	-0.007	-0.15-1495.	-0.1310	
12.19	2.326	0.047	-0.401	0.933	-0.004	-0.08-1495.	-0.1308	
13.21	2.234	0.050	-0.447	1.000	-0.004	-0.07-1502.	-0.1316	
14.23	2.130	0.053	-0.500	1.065	-0.004	-0.07-1502.	-0.1316	
15.22	2.028	0.055	-0.553	1.122	-0.003	-0.05-1508.	-0.1321	

(c)  $p \approx -237$  rev/s

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.95	3.478	-0.020	0.088	-0.308	0.020	-0.96-1942.	-0.1698	
-2.96	3.685	-0.015	0.062	-0.229	0.017	-1.12-1935.	-0.1693	
-1.94	4.030	-0.009	0.036	-0.145	0.013	-1.41-1942.	-0.1698	
-0.94	6.219	-0.005	0.010	-0.065	0.011	-2.35-1935.	-0.1693	
0.07	1.131	0.001	-0.013	0.015	0.008	13.13-1935.	-0.1693	
1.10	2.512	0.006	-0.040	0.100	0.005	0.77-1929.	-0.1687	
2.09	2.765	0.011	-0.064	0.177	0.002	0.19-1935.	-0.1693	
3.10	2.824	0.017	-0.092	0.259	-0.002	-0.09-1935.	-0.1693	
4.10	2.865	0.023	-0.118	0.339	-0.005	-0.23-1935.	-0.1693	
5.11	2.744	0.028	-0.150	0.412	-0.008	-0.27-1935.	-0.1693	
6.14	2.704	0.035	-0.181	0.491	-0.011	-0.33-1935.	-0.1693	
7.15	2.645	0.043	-0.215	0.569	-0.016	-0.38-1935.	-0.1693	
8.15	2.576	0.049	-0.251	0.646	-0.020	-0.40-1935.	-0.1693	
9.20	2.488	0.056	-0.290	0.722	-0.021	-0.37-1935.	-0.1693	
10.17	2.390	0.060	-0.328	0.784	-0.018	-0.30-1942.	-0.1698	
11.20	2.318	0.062	-0.370	0.857	-0.014	-0.23-1935.	-0.1693	
12.20	2.252	0.062	-0.410	0.925	-0.009	-0.15-1929.	-0.1687	
13.21	2.181	0.063	-0.455	0.992	-0.006	-0.10-1935.	-0.1693	
14.23	2.085	0.066	-0.506	1.054	-0.005	-0.08-1929.	-0.1687	
15.22	1.993	0.069	-0.559	1.114	-0.004	-0.06-1929.	-0.1687	

(d)  $p \approx -308$  rev/s

TABLE 6. AERODYNAMIC COEFFICIENTS,  $M = 0.95$ 

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.97	4.352	-0.001	0.079	-0.344	-0.000	0.29	0.-0.0000	
-2.97	4.858	0.001	0.053	-0.259	-0.002	-2.05	0.-0.0000	
-1.94	4.952	0.001	0.033	-0.163	-0.002	-1.62	0.-0.0000	
-0.94	5.069	0.001	0.013	-0.067	-0.001	-1.20	0.-0.0000	
0.07	10.657	0.001	-0.003	0.029	-0.000	-0.67	0.-0.0000	
1.09	6.195	0.000	-0.021	0.128	0.000	0.48	0.-0.0000	
2.10	5.280	0.000	-0.042	0.223	0.000	7.76	0.-0.0000	
3.11	4.613	0.001	-0.067	0.309	-0.000	-0.39	0.-0.0000	
4.10	4.240	0.004	-0.093	0.395	-0.003	-0.98	0.-0.0000	
5.12	3.842	0.003	-0.123	0.473	-0.003	-1.00	0.-0.0000	
6.15	3.675	0.007	-0.152	0.559	-0.008	-1.21	0.-0.0000	
7.16	3.471	0.008	-0.184	0.638	-0.011	-1.25	0.-0.0000	
8.17	3.344	0.010	-0.216	0.723	-0.012	-1.29	0.-0.0000	
9.17	3.080	0.007	-0.255	0.787	-0.009	-1.31	0.-0.0000	
10.18	2.960	0.008	-0.292	0.865	-0.010	-1.22	0.-0.0000	
11.20	2.776	0.010	-0.337	0.935	-0.010	-1.07	0.-0.0000	
12.20	2.508	0.013	-0.386	1.002	-0.016	-1.19	0.-0.0000	
13.23	2.406	0.019	-0.448	1.079	-0.024	-1.21	0.-0.0000	
14.23	2.246	0.014	-0.512	1.150	-0.021	-1.50	0.-0.0000	
15.25	2.132	0.006	-0.570	1.218	-0.008	-1.34	0.-0.0000	

(a)  $p = 0$ 

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.97	4.284	-0.020	0.079	-0.340	0.024	-1.20	-936.-0.0784	
-2.97	4.959	-0.014	0.052	-0.256	0.010	-1.32	-936.-0.0783	
-1.94	5.464	-0.009	0.030	-0.164	0.014	-1.52	-936.-0.0784	
-0.94	5.746	-0.004	0.012	-0.069	0.009	-2.19	-930.-0.0778	
0.07	3.204	-0.000	-0.007	0.024	0.006	-14.13	-930.-0.0779	
1.10	4.636	0.004	-0.026	0.121	0.002	0.54	-936.-0.0783	
2.10	4.281	0.008	-0.048	0.204	-0.001	-0.07	-930.-0.0778	
3.12	4.130	0.014	-0.072	0.295	-0.007	-0.47	-924.-0.0773	
4.11	3.946	0.022	-0.097	0.384	-0.015	-0.66	-930.-0.0779	
5.12	3.622	0.026	-0.127	0.460	-0.018	-0.69	-936.-0.0784	
6.14	3.508	0.037	-0.156	0.549	-0.029	-0.80	-936.-0.0784	
7.16	3.400	0.048	-0.187	0.636	-0.041	-0.86	-936.-0.0784	
8.17	3.275	0.048	-0.218	0.713	-0.039	-0.81	-942.-0.0790	
9.17	3.008	0.044	-0.255	0.789	-0.032	-0.72	-942.-0.0788	
10.18	2.944	0.016	-0.294	0.865	0.006	0.37	-942.-0.0788	
11.20	2.773	0.003	-0.339	0.940	0.024	7.24	-942.-0.0790	
12.21	2.573	0.004	-0.389	1.002	0.025	6.17	-942.-0.0788	
13.23	2.402	-0.003	-0.444	1.067	0.036	-12.65	-942.-0.0788	
14.25	2.260	-0.015	-0.503	1.137	0.052	-3.43	-949.-0.0794	
15.25	2.136	-0.018	-0.562	1.200	0.058	-3.25	-949.-0.0794	

(b)  $p \approx -149$  rev/s

TABLE 6(CONTD.).

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.99	4.180	-0.028	0.080	-0.334	0.032	-1.14-1508.	-0.1261	
-2.96	4.613	-0.020	0.054	-0.249	0.025	-1.22-1508.	-0.1261	
-1.94	5.265	-0.013	0.030	-0.159	0.019	-1.41-1508.	-0.1261	
-0.94	6.253	-0.006	0.011	-0.068	0.012	-2.03-1502.	-0.1256	
0.06	2.425	-0.000	-0.009	0.021	0.008	-512.79-1508.	-0.1261	
1.08	4.345	0.008	-0.027	0.118	0.000	0.02-1508.	-0.1261	
2.10	3.769	0.012	-0.053	0.199	-0.002	-0.14-1502.	-0.1256	
3.12	3.712	0.020	-0.078	0.289	-0.009	-0.44-1495.	-0.1251	
4.11	3.645	0.029	-0.103	0.374	-0.017	-0.61-1502.	-0.1256	
5.12	3.372	0.033	-0.133	0.449	-0.020	-0.60-1502.	-0.1256	
6.14	3.279	0.044	-0.163	0.534	-0.031	-0.70-1495.	-0.1251	
7.16	3.203	0.056	-0.194	0.620	-0.042	-0.75-1502.	-0.1256	
8.17	3.150	0.066	-0.227	0.705	-0.051	-0.78-1495.	-0.1251	
9.18	2.966	0.067	-0.264	0.780	-0.048	-0.72-1502.	-0.1256	
10.19	2.856	0.045	-0.301	0.860	-0.016	-0.35-1502.	-0.1256	
11.21	2.738	0.028	-0.344	0.942	0.007	0.23-1502.	-0.1256	
12.21	2.564	0.027	-0.392	1.006	0.012	0.42-1495.	-0.1251	
13.24	2.354	0.028	-0.453	1.067	0.014	0.49-1495.	-0.1251	
14.24	2.225	0.021	-0.509	1.132	0.025	1.17-1495.	-0.1251	
15.24	2.107	0.006	-0.571	1.203	0.047	8.23-1495.	-0.1251	

(c)  $p \approx -239$  rev/s

$a^0$	C.P. <sub>Z</sub>	C <sub>Y</sub>	C <sub>Z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>Y</sub>	p(rad/s)	p'
-3.99	4.265	-0.034	0.079	-0.337	0.037	-1.08-1954.	-0.1635	
-2.96	4.791	-0.026	0.053	-0.252	0.030	-1.17-1954.	-0.1635	
-1.94	5.625	-0.017	0.029	-0.163	0.022	-1.32-1954.	-0.1635	
-0.95	8.655	-0.008	0.008	-0.073	0.014	-1.79-1954.	-0.1635	
0.07	1.830	0.001	-0.011	0.020	0.007	8.46-1954.	-0.1632	
1.10	3.480	0.010	-0.032	0.112	-0.000	-0.03-1954.	-0.1632	
2.08	3.784	0.019	-0.053	0.200	-0.009	-0.48-1948.	-0.1627	
3.11	3.576	0.026	-0.080	0.284	-0.014	-0.54-1954.	-0.1635	
4.10	3.423	0.034	-0.107	0.365	-0.021	-0.60-1948.	-0.1627	
5.12	3.312	0.047	-0.136	0.450	-0.033	-0.70-1948.	-0.1627	
6.13	3.209	0.061	-0.167	0.536	-0.047	-0.77-1954.	-0.1632	
7.15	3.034	0.064	-0.201	0.608	-0.045	-0.71-1948.	-0.1627	
8.17	2.935	0.075	-0.236	0.694	-0.054	-0.73-1954.	-0.1632	
9.18	2.824	0.080	-0.273	0.772	-0.055	-0.70-1954.	-0.1632	
10.20	2.709	0.073	-0.315	0.852	-0.041	-0.56-1954.	-0.1632	
11.23	2.610	0.053	-0.355	0.926	-0.012	-0.22-1948.	-0.1627	
12.21	2.486	0.039	-0.400	0.996	0.009	0.24-1954.	-0.1632	
13.24	2.346	0.034	-0.451	1.059	0.020	0.61-1954.	-0.1632	
14.24	2.207	0.031	-0.510	1.127	0.027	0.66-1954.	-0.1632	
15.24	2.096	0.027	-0.572	1.200	0.036	1.35-1954.	-0.1632	

(d)  $p \approx -311$  rev/s



TABLE 7. AERODYNAMIC COEFFICIENTS,  $M = 1.4$ 

$\alpha^\circ$	C.P. <sub>z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>y</sub>	$p$ (rad/s)	$p'$
-3.96	1.624	0.002	0.166	-0.270	-0.006	-2.68	0.-0.0000	
-2.95	1.667	0.002	0.119	-0.198	-0.005	-2.46	0.-0.0000	
-1.94	1.673	0.002	0.075	-0.125	-0.005	-2.35	0.-0.0000	
-0.94	1.718	0.002	0.031	-0.053	-0.004	-2.44	0.-0.0000	
0.06	1.495	0.002	-0.014	0.020	-0.004	-2.38	0.-0.0000	
1.09	1.623	0.001	-0.057	0.092	-0.003	-2.34	0.-0.0000	
2.12	1.620	0.001	-0.103	0.166	-0.003	-2.47	0.-0.0000	
3.13	1.621	0.001	-0.146	0.237	-0.002	-2.60	0.-0.0000	
4.13	1.601	0.001	-0.193	0.309	-0.002	-2.21	0.-0.0000	
5.15	1.583	0.002	-0.241	0.381	-0.002	-1.00	0.-0.0000	
6.16	1.552	0.001	-0.291	0.452	-0.002	-1.76	0.-0.0000	
7.20	1.521	0.001	-0.345	0.525	-0.001	-1.40	0.-0.0000	
8.22	1.485	0.001	-0.401	0.596	-0.001	-1.32	0.-0.0000	
9.22	1.445	0.001	-0.461	0.665	-0.002	-1.88	0.-0.0000	
10.23	1.402	-0.000	-0.525	0.735	-0.002	6.13	0.-0.0000	
11.28	1.355	-0.001	-0.594	0.805	-0.003	4.59	0.-0.0000	
12.27	1.306	-0.001	-0.666	0.870	-0.002	2.66	0.-0.0000	
13.30	1.253	-0.001	-0.748	0.937	-0.002	2.23	0.-0.0000	
14.30	1.198	-0.004	-0.834	1.000	-0.002	0.42	0.-0.0000	
15.32	1.137	-0.003	-0.933	1.061	-0.002	0.67	0.-0.0000	

(a)  $p = 0$ 

$\alpha^\circ$	C.P. <sub>z</sub>	$C_Y$	$C_Z$	$C_m$	$C_n$	C.P. <sub>y</sub>	$p$ (rad/s)	$p'$
-4.00	1.670	-0.003	0.163	-0.273	0.000	-0.16	-942.-0.0586	
-2.98	1.699	-0.001	0.118	-0.201	0.000	-0.10	-936.-0.0582	
-1.96	1.747	-0.000	0.073	-0.128	0.000	-0.04	-936.-0.0582	
-0.95	1.785	0.001	0.030	-0.054	0.000	0.32	-936.-0.0582	
0.06	1.661	0.002	-0.012	0.020	0.000	0.06	-942.-0.0586	
1.07	1.664	0.002	-0.056	0.094	-0.000	-0.02	-936.-0.0582	
2.11	1.681	0.004	-0.100	0.169	-0.000	-0.07	-942.-0.0586	
3.11	1.663	0.005	-0.145	0.240	-0.000	-0.10	-942.-0.0586	
4.12	1.625	0.006	-0.192	0.311	-0.001	-0.10	-936.-0.0582	
5.14	1.591	0.008	-0.241	0.383	-0.001	-0.14	-936.-0.0582	
6.19	1.563	0.010	-0.292	0.457	-0.001	-0.15	-942.-0.0586	
7.19	1.525	0.012	-0.345	0.527	-0.002	-0.17	-949.-0.0589	
8.21	1.488	0.014	-0.401	0.598	-0.002	-0.17	-955.-0.0593	
9.21	1.441	0.016	-0.463	0.668	-0.003	-0.16	-955.-0.0593	
10.23	1.374	0.019	-0.529	0.737	-0.003	-0.17	-961.-0.0597	
11.26	1.340	0.021	-0.597	0.805	-0.004	-0.21	-955.-0.0593	
12.26	1.304	0.022	-0.668	0.871	-0.005	-0.24	-955.-0.0592	
13.29	1.254	0.022	-0.748	0.938	-0.005	-0.23	-955.-0.0593	
14.30	1.190	0.022	-0.835	1.001	-0.003	-0.15	-961.-0.0597	
15.31	1.143	0.020	-0.931	1.064	0.003	0.13	-961.-0.0597	

(b)  $p \approx -151$  rev/s

TABLE 7(CONTD.).

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-4.00	1.744	-0.006	0.159	-0.277	0.004	-0.61-1508.-0.0935		
-2.98	1.788	-0.005	0.115	-0.205	0.003	-0.74-1508.-0.0935		
-1.96	1.836	-0.003	0.071	-0.131	0.003	-1.12-1508.-0.0935		
-0.95	2.039	-0.001	0.027	-0.056	0.002	-3.02-1508.-0.0935		
0.07	1.467	0.001	-0.013	0.019	0.002	1.72-1508.-0.0935		
1.10	1.644	0.003	-0.058	0.095	0.001	0.52-1508.-0.0935		
2.11	1.677	0.005	-0.100	0.168	0.001	0.18-1514.-0.0939		
3.12	1.360	0.001	-0.166	0.226	0.012	13.77-1508.-0.0935		
4.11	1.640	0.009	-0.190	0.312	-0.001	-0.11-1508.-0.0935		
5.14	1.612	0.011	-0.239	0.385	-0.002	-0.16-1508.-0.0935		
6.16	1.571	0.014	-0.290	0.456	-0.003	-0.21-1514.-0.0939		
7.19	1.536	0.016	-0.344	0.528	-0.004	-0.24-1514.-0.0939		
8.20	1.498	0.019	-0.399	0.598	-0.005	-0.25-1514.-0.0939		
9.21	1.443	0.023	-0.462	0.667	-0.006	-0.24-1521.-0.0943		
10.23	1.395	0.027	-0.528	0.736	-0.007	-0.25-1521.-0.0943		
11.26	1.348	0.030	-0.597	0.805	-0.007	-0.25-1527.-0.0947		
12.26	1.301	0.033	-0.669	0.870	-0.008	-0.24-1527.-0.0947		
13.29	1.254	0.032	-0.749	0.939	-0.005	-0.17-1527.-0.0947		
14.31	1.204	0.028	-0.835	1.005	0.002	0.06-1527.-0.0947		
15.31	1.156	0.016	-0.927	1.071	0.019	1.16-1527.-0.0947		

(c)  $p \approx -241$  rev/s

$\alpha^0$	C.P. <sub>z</sub>	C <sub>y</sub>	C <sub>z</sub>	C <sub>m</sub>	C <sub>n</sub>	C.P. <sub>y</sub>	p(rad/s)	p'
-3.99	1.780	-0.010	0.158	-0.282	0.007	-0.70-1923.-0.1191		
-2.98	1.884	-0.007	0.111	-0.209	0.006	-0.77-1923.-0.1191		
-1.96	1.961	-0.005	0.068	-0.134	0.004	-0.91-1923.-0.1191		
-0.95	2.353	-0.002	0.025	-0.059	0.003	-1.55-1923.-0.1191		
0.07	1.244	0.001	-0.014	0.018	0.002	2.48-1923.-0.1191		
1.08	1.609	0.003	-0.058	0.092	0.001	0.20-1916.-0.1187		
2.11	1.667	0.006	-0.101	0.168	-0.000	-0.07-1916.-0.1187		
3.15	1.572	0.009	-0.146	0.244	-0.002	-0.21-1916.-0.1187		
4.12	1.658	0.011	-0.189	0.313	-0.003	-0.22-1923.-0.1191		
5.14	1.626	0.014	-0.237	0.386	-0.004	-0.27-1916.-0.1187		
6.19	1.585	0.017	-0.289	0.459	-0.005	-0.29-1923.-0.1191		
7.20	1.537	0.020	-0.344	0.528	-0.006	-0.30-1923.-0.1191		
8.20	1.492	0.023	-0.401	0.598	-0.007	-0.29-1916.-0.1187		
9.21	1.440	0.026	-0.461	0.667	-0.007	-0.28-1916.-0.1187		
10.24	1.396	0.030	-0.528	0.737	-0.007	-0.24-1923.-0.1191		
11.26	1.348	0.033	-0.598	0.806	-0.006	-0.19-1923.-0.1191		
12.27	1.301	0.035	-0.671	0.872	-0.004	-0.12-1916.-0.1187		
13.29	1.257	0.035	-0.749	0.941	-0.001	-0.02-1916.-0.1187		
14.30	1.216	0.027	-0.831	1.010	0.012	0.42-1916.-0.1187		
15.33	1.160	0.013	-0.923	1.078	0.032	2.51-1910.-0.1183		

(d)  $p \approx -305$  rev/s

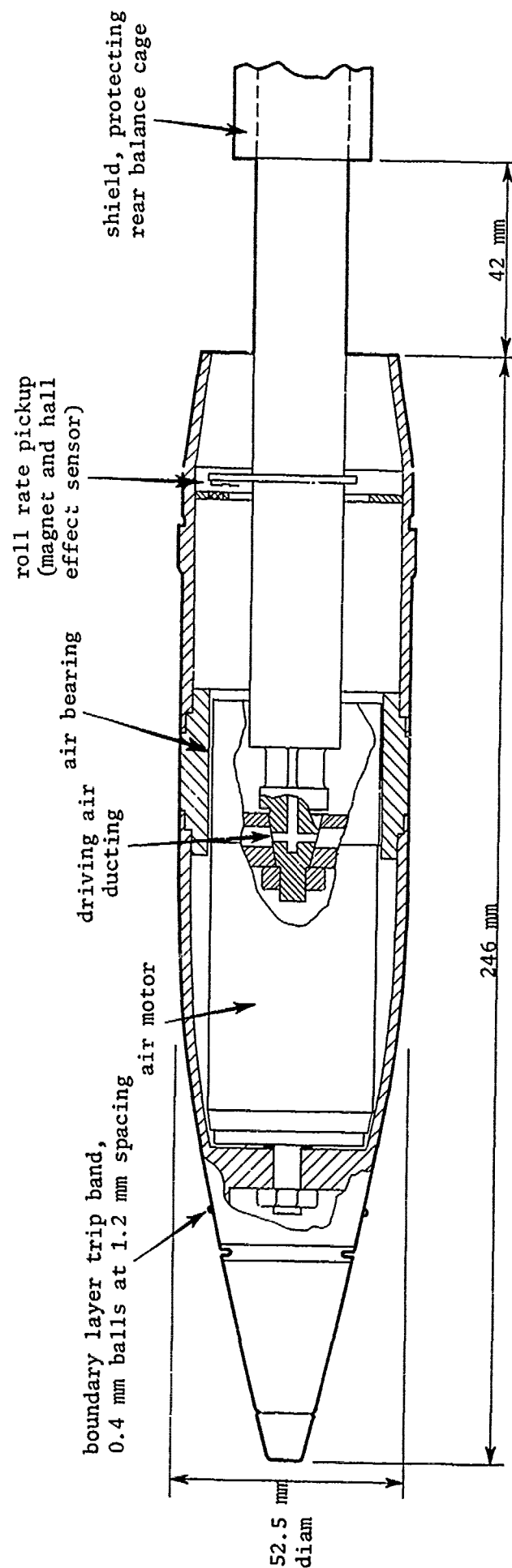


Figure 1. 105mm shell model, showing internal details

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Figure 2

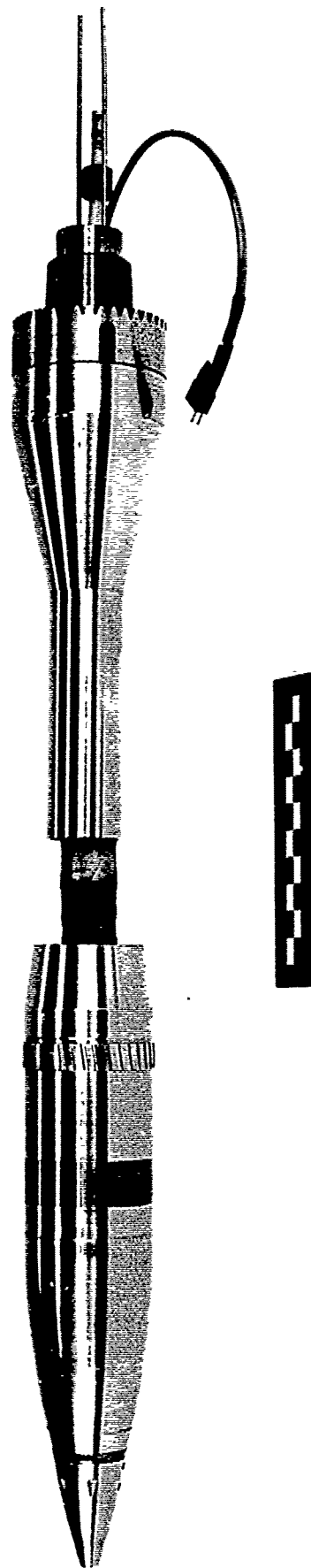


Figure 2. Assembly of model, balance and balance shield

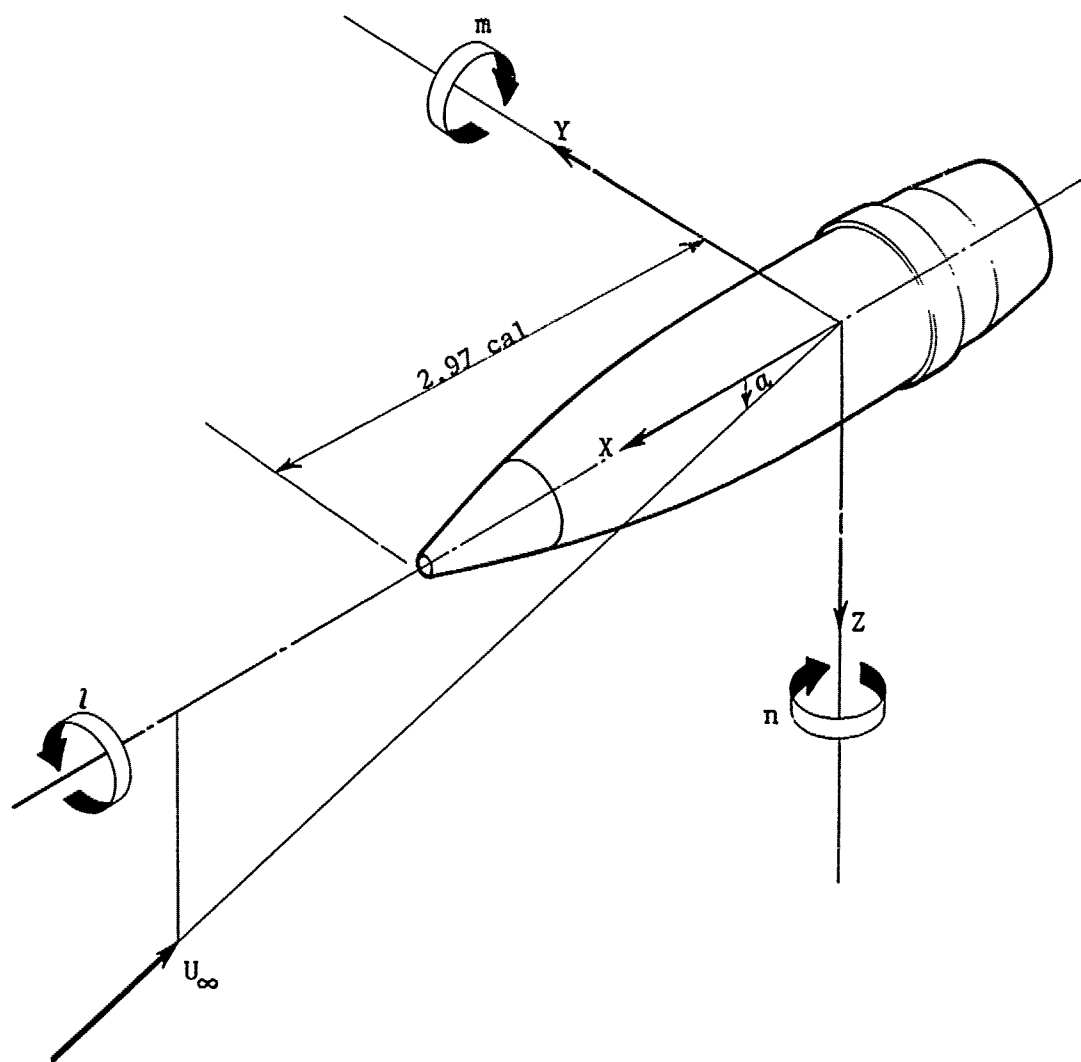


Figure 3. Axis system used in presentation of results

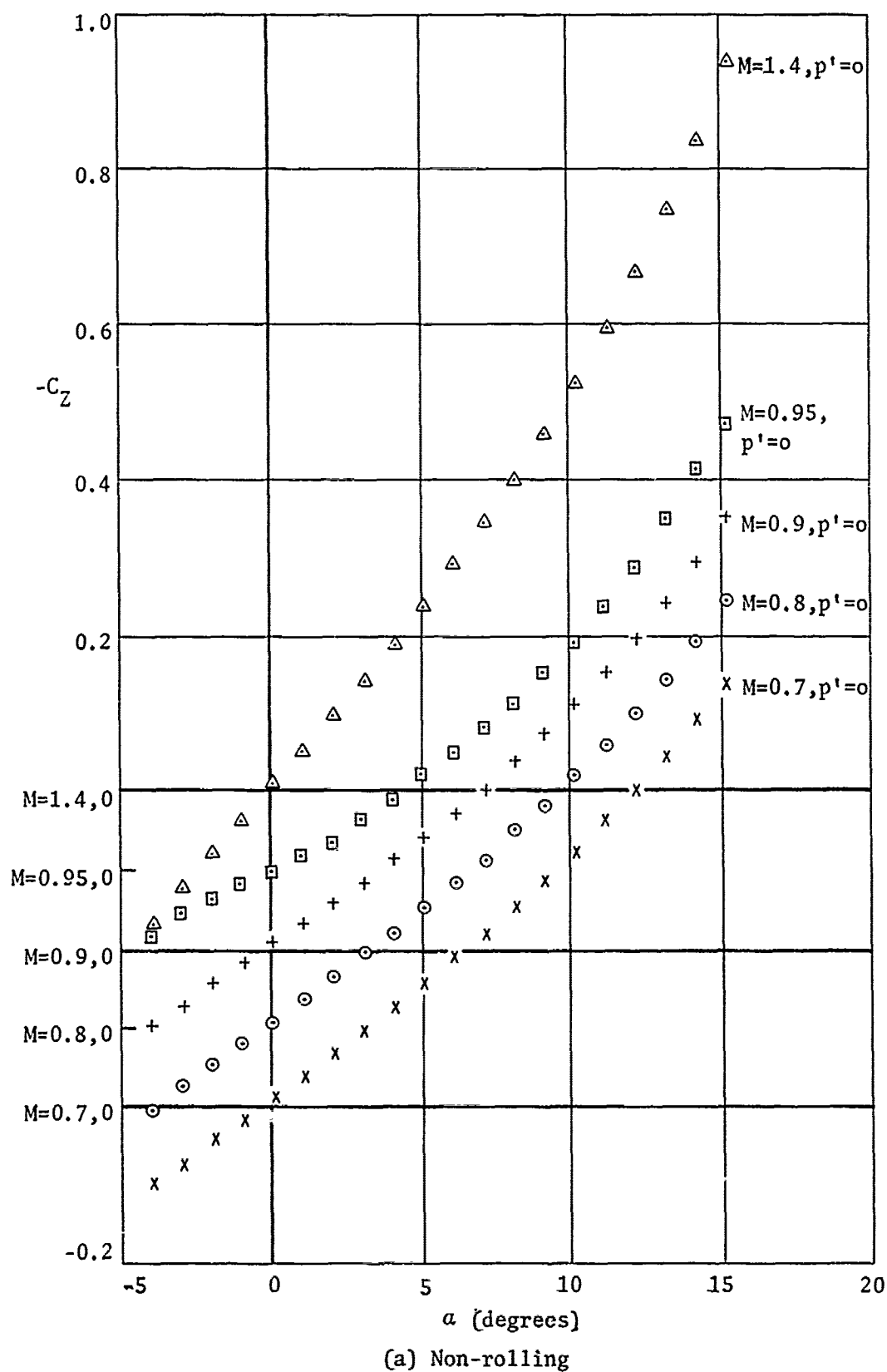
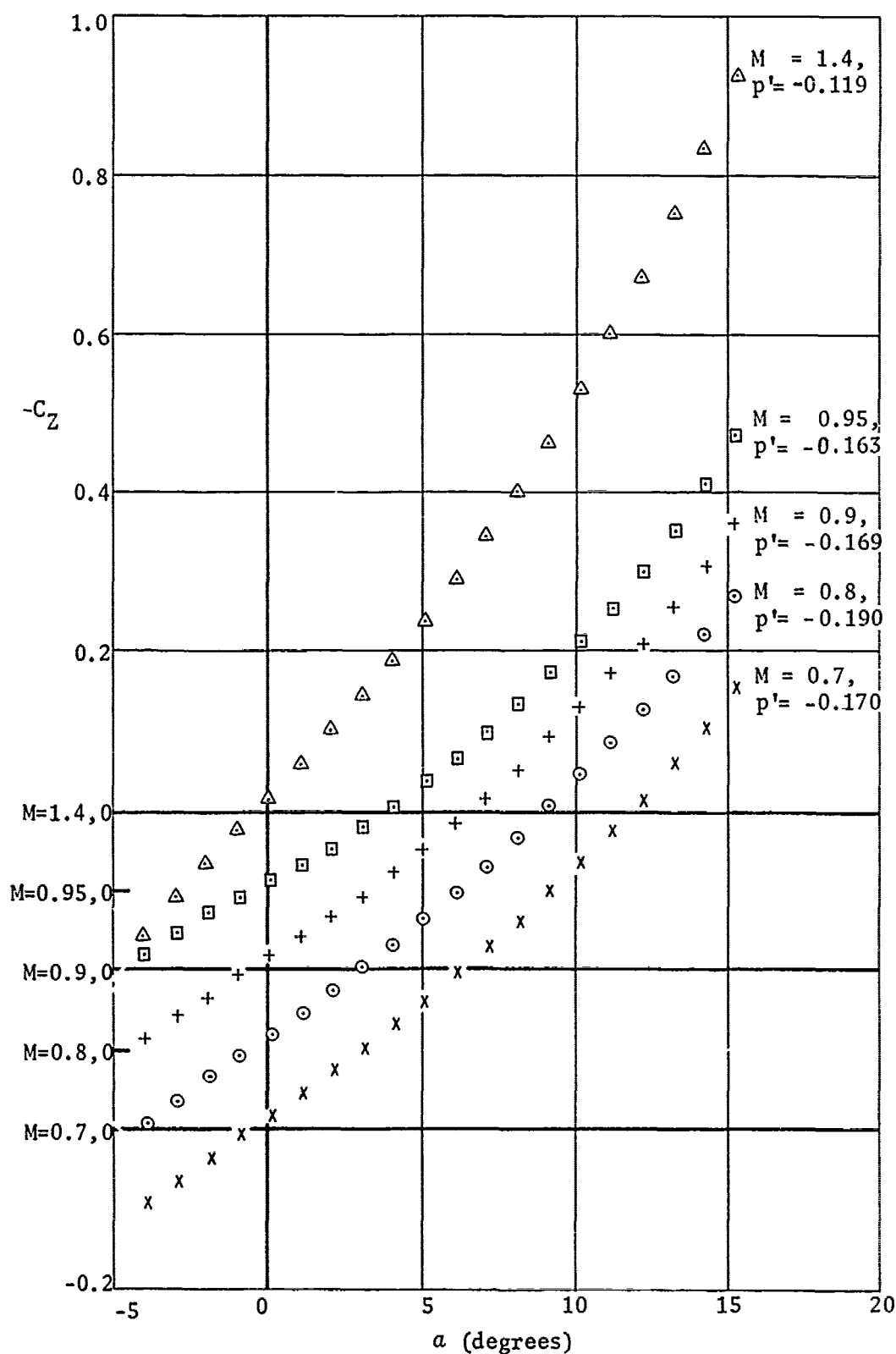


Figure 4. Variation of normal force coefficient with incidence, Mach no. and roll rate



(b) Rolling - rates as shown

Figure 4(Contd.). Variation of normal force coefficient with incidence, Mach. no. and roll rate

Figure 5

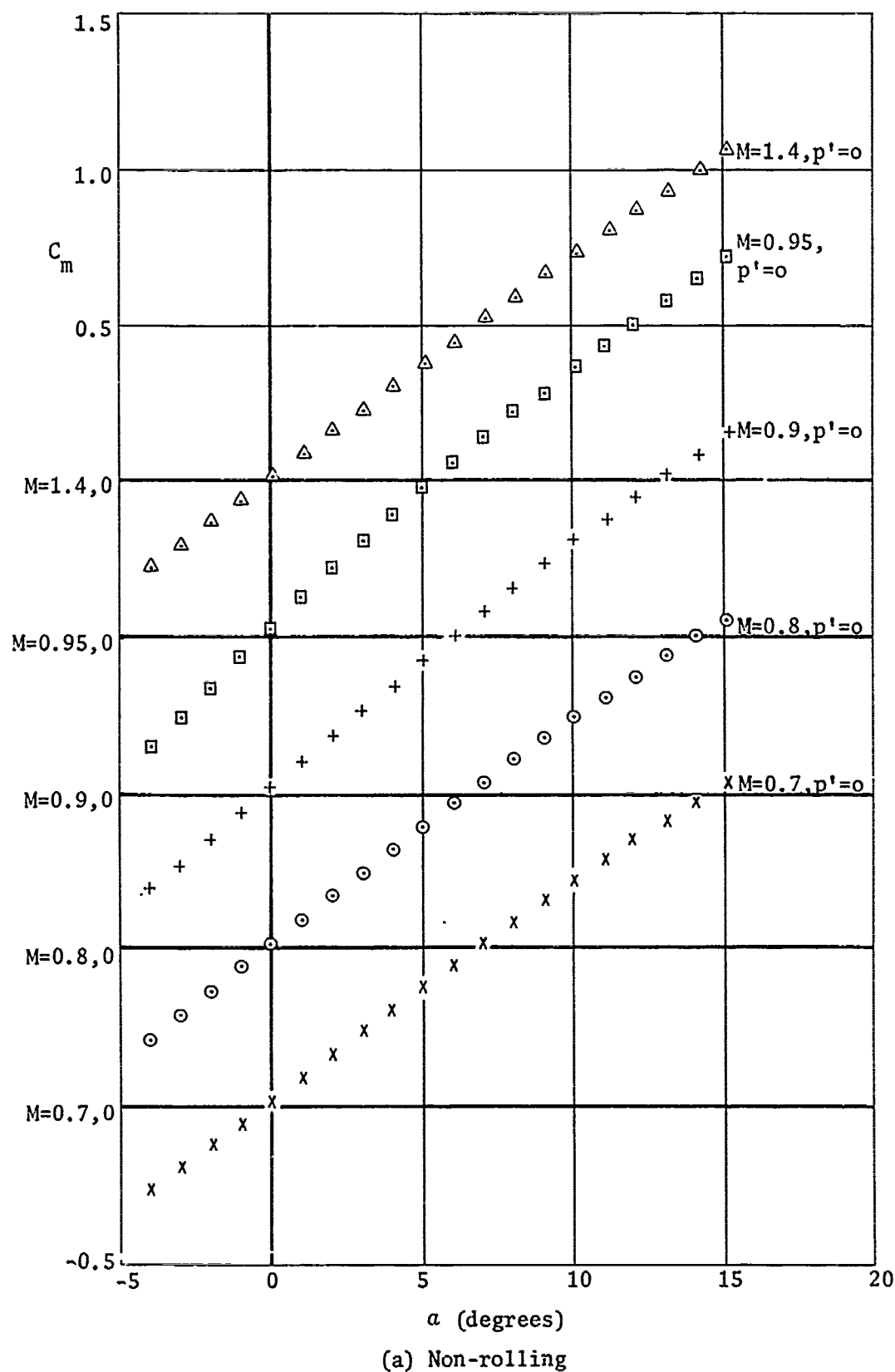


Figure 5. Variation of pitching moment coefficient with incidence, Mach no. and roll rate



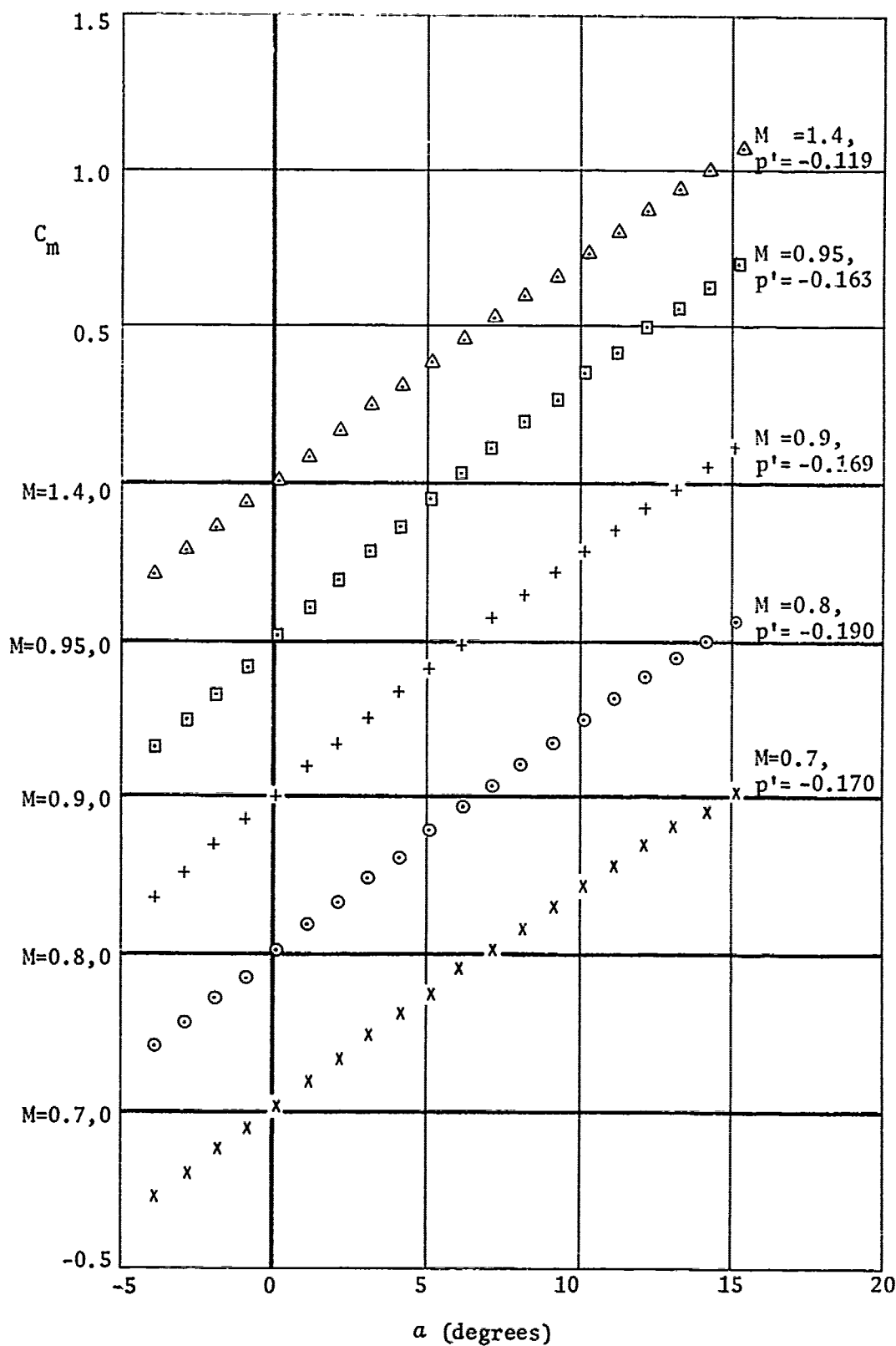
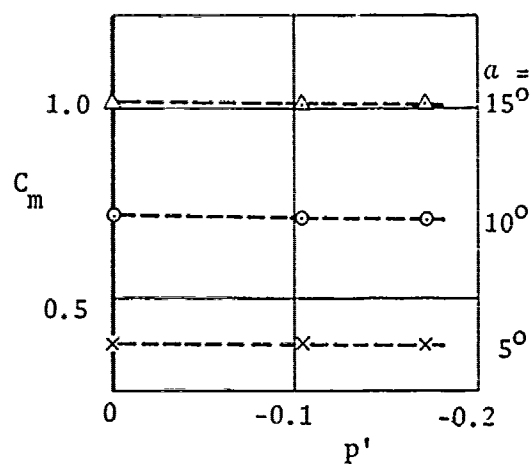
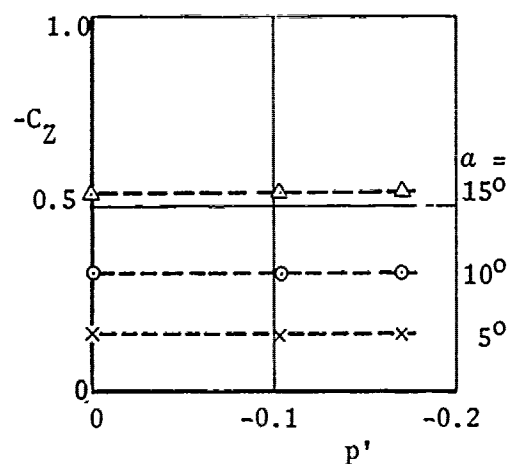
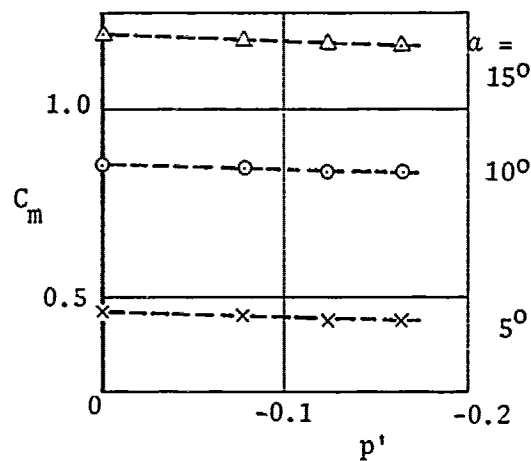
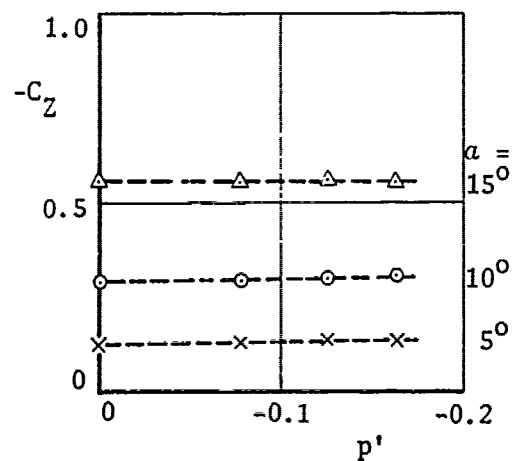


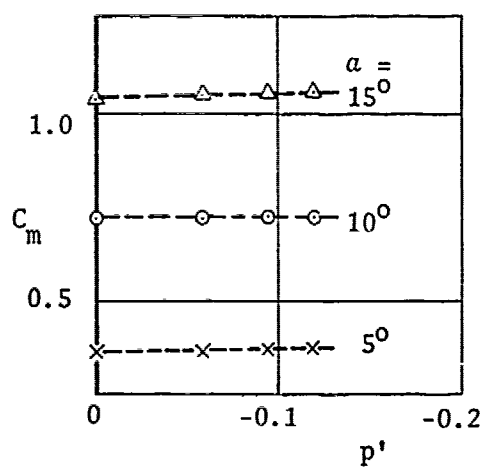
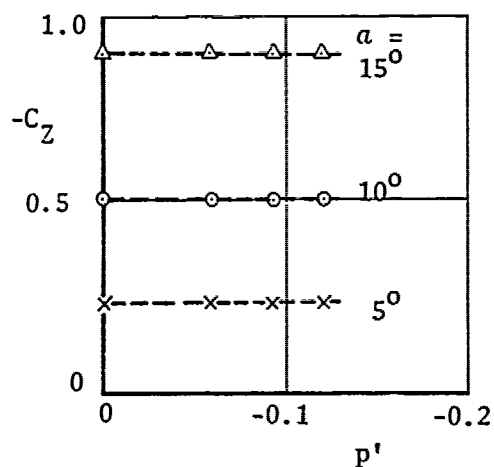
Figure 5(Contd.). Variation of pitching moment coefficient with incidence, Mach no. and roll rate



(a)  $M = 0.70$

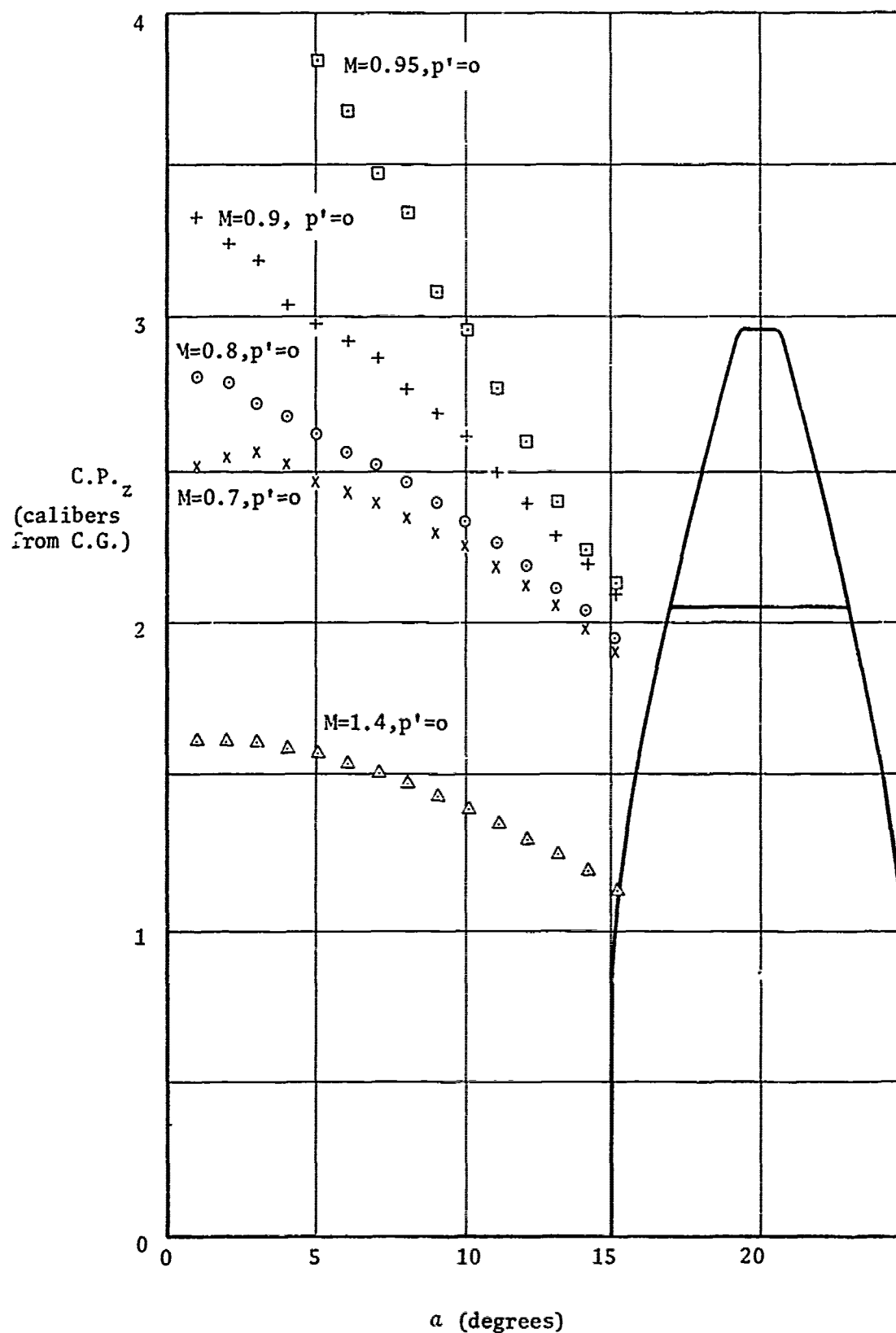


(b)  $M = 0.95$



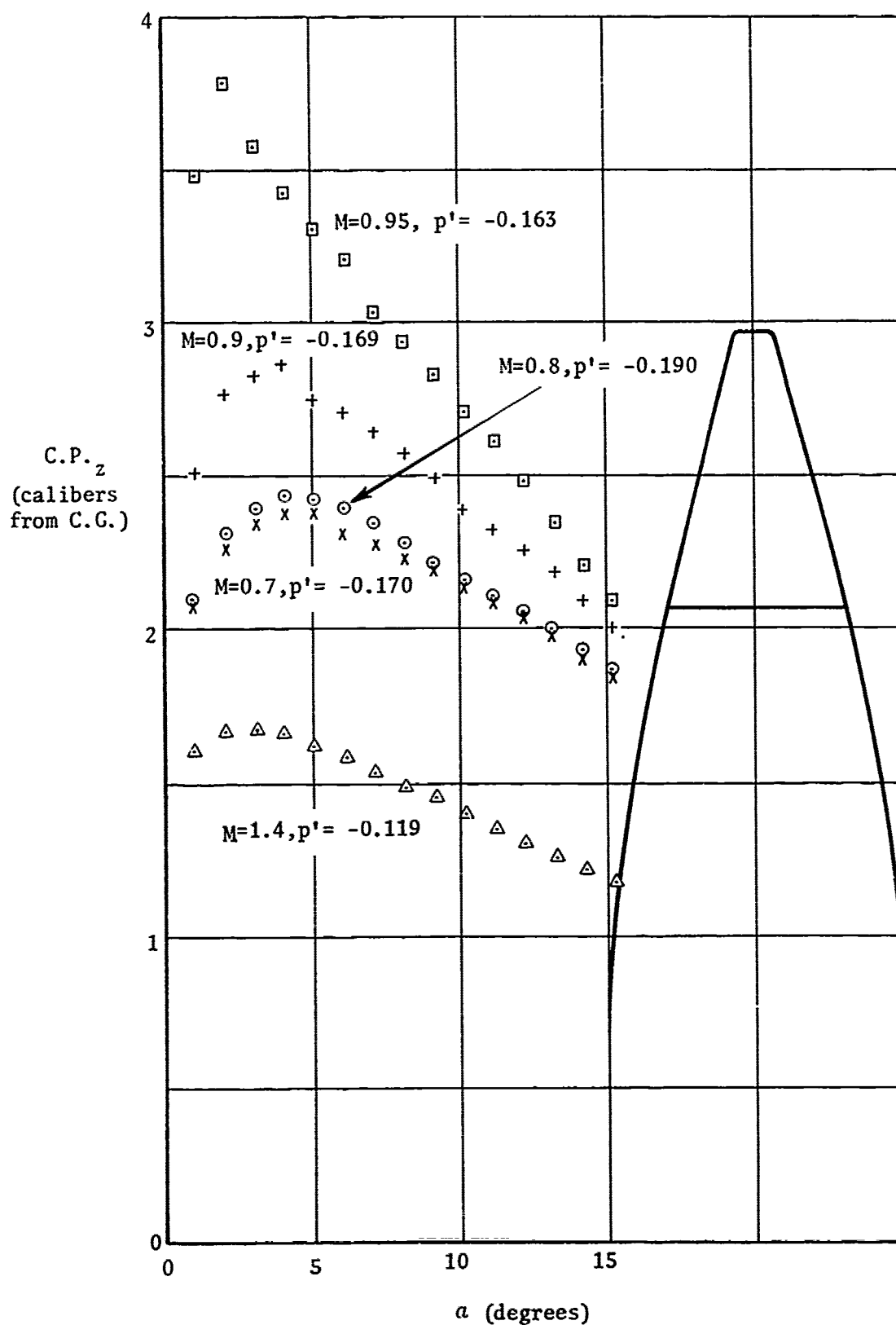
(c)  $M = 1.4$

Figure 6. Effect of roll rate on normal force and pitching moment coefficients



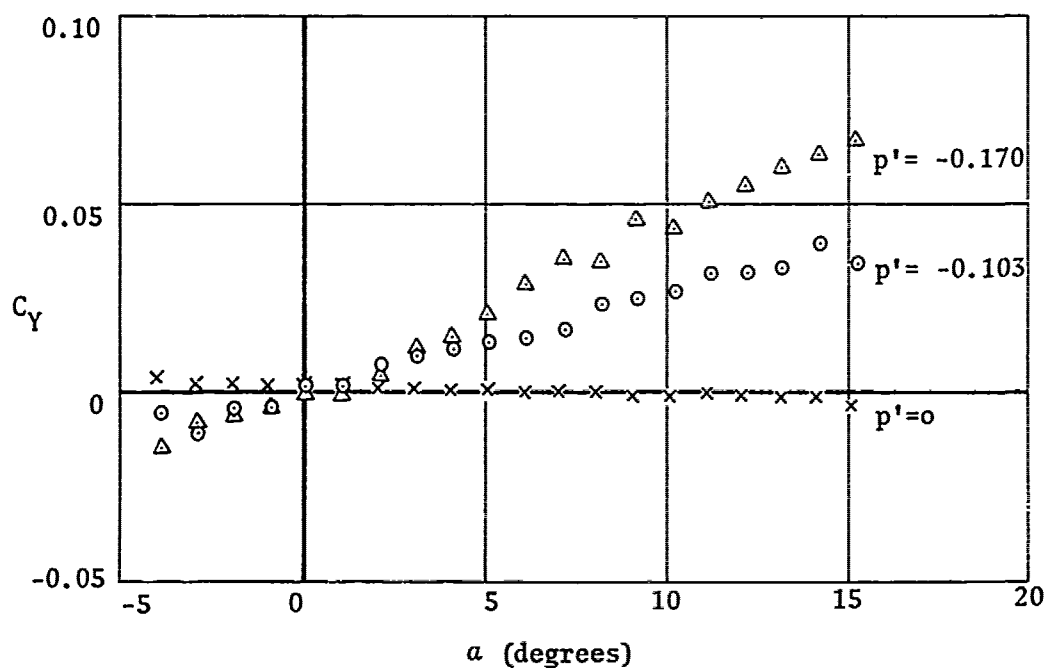
(a) Non-rolling

Figure 7. Variation of centre of pressure in pitch plane with incidence, Mach no. and roll rate

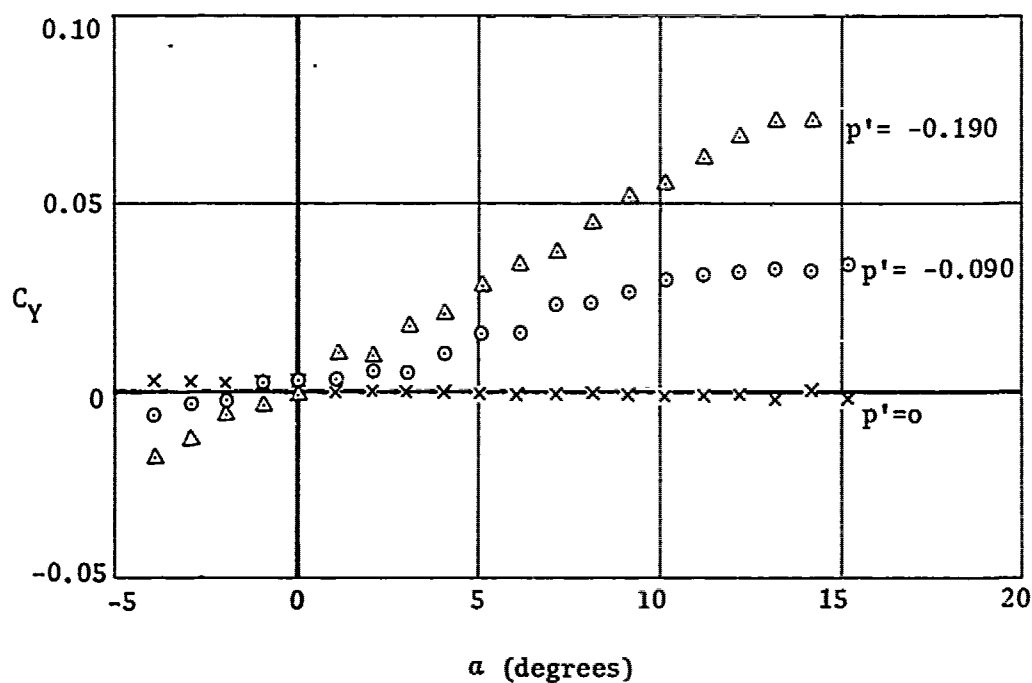


(b) Rolling - rates as shown

Figure 7(Contd.). Variation of centre of pressure in pitch plane with incidence, Mach no. and roll rate



(a)  $M = 0.7$



(b)  $M = 0.8$

Figure 8. Variation of side force coefficient with incidence, Mach no. and roll rate

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Figure 8(Contd.).

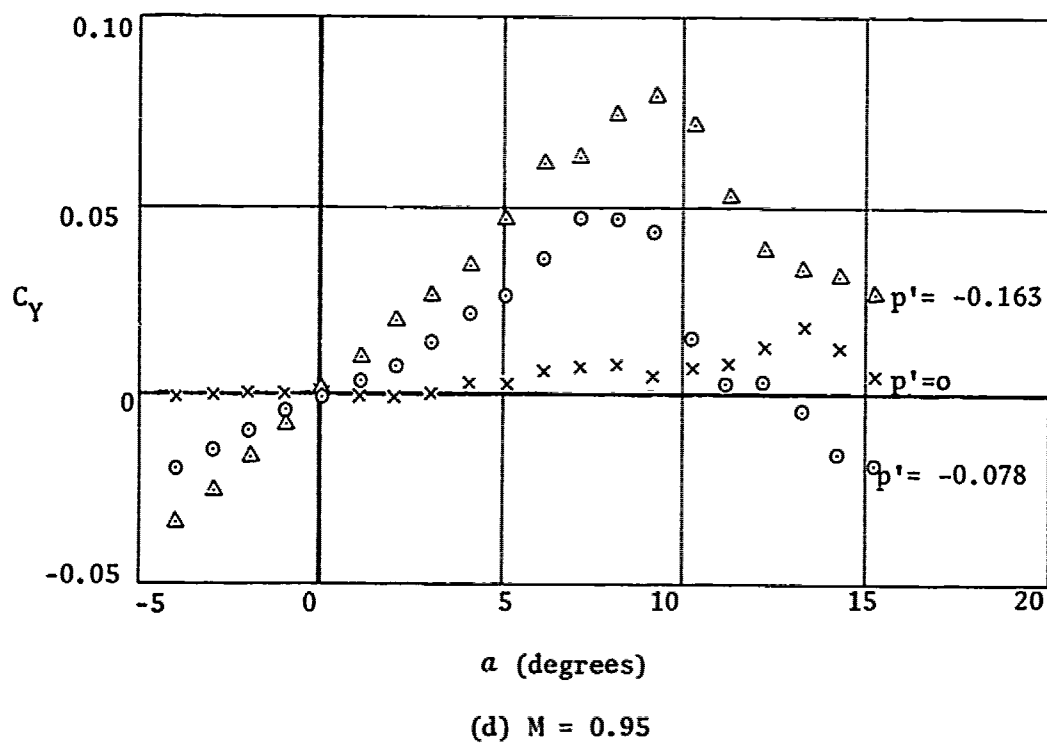
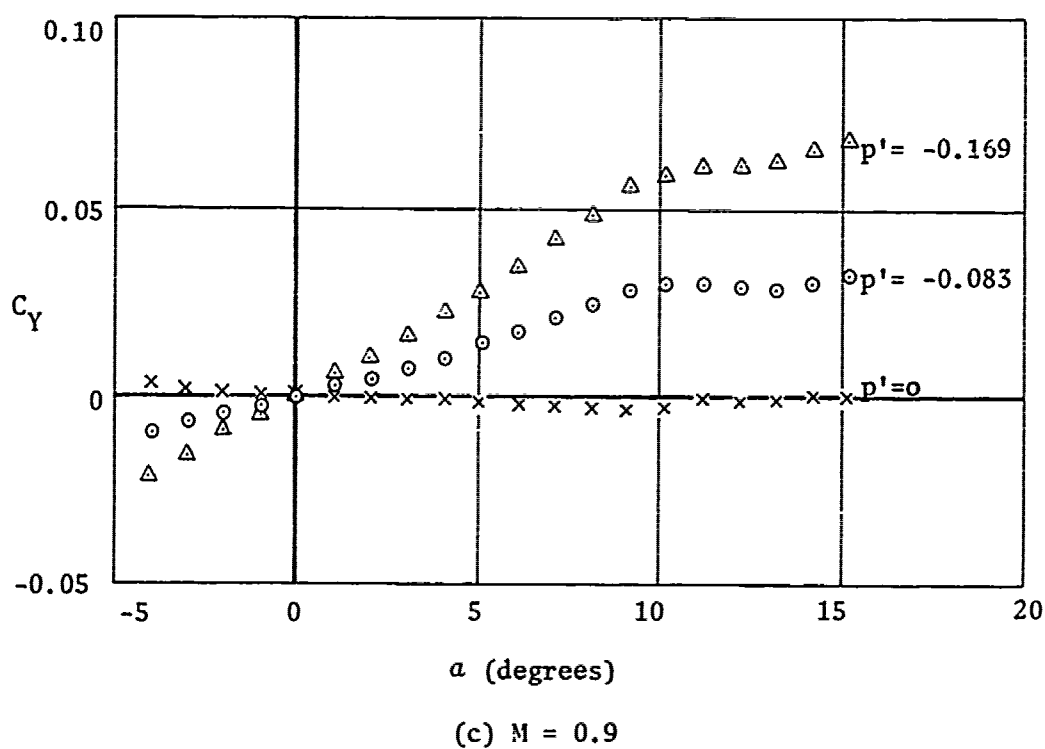
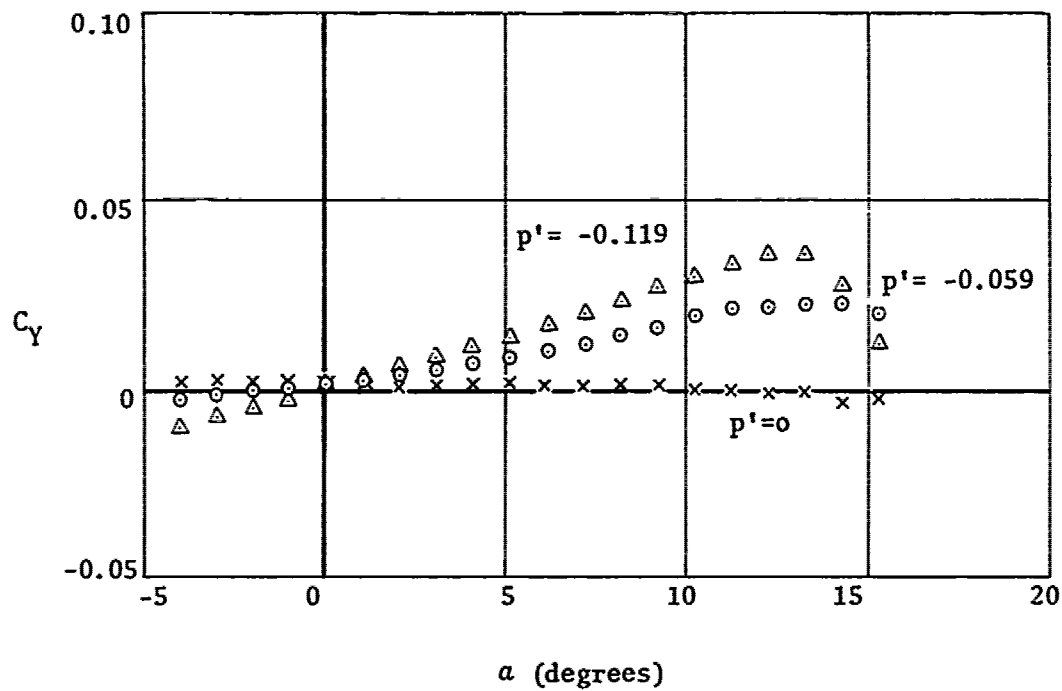


Figure 8(Contd.). Variation of side force coefficient with incidence, Mach no. and roll rate



(e)  $M = 1.4$

Figure 8(Contd.). Variation of side force coefficient with incidence, Mach no. and roll rate

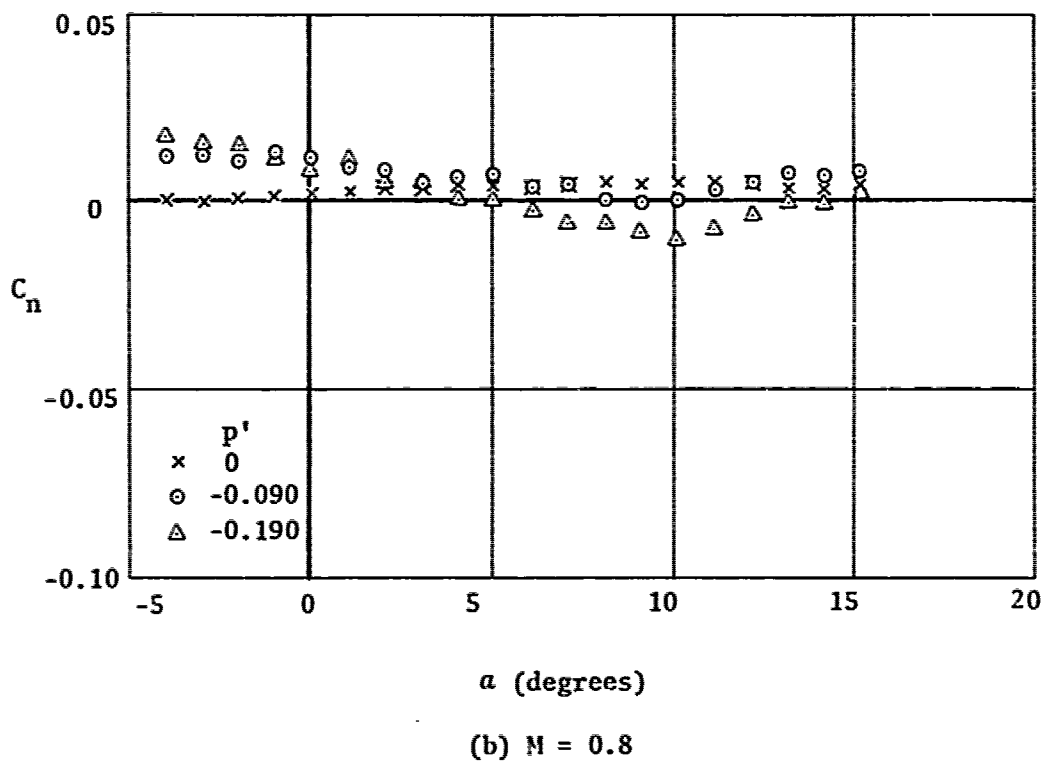
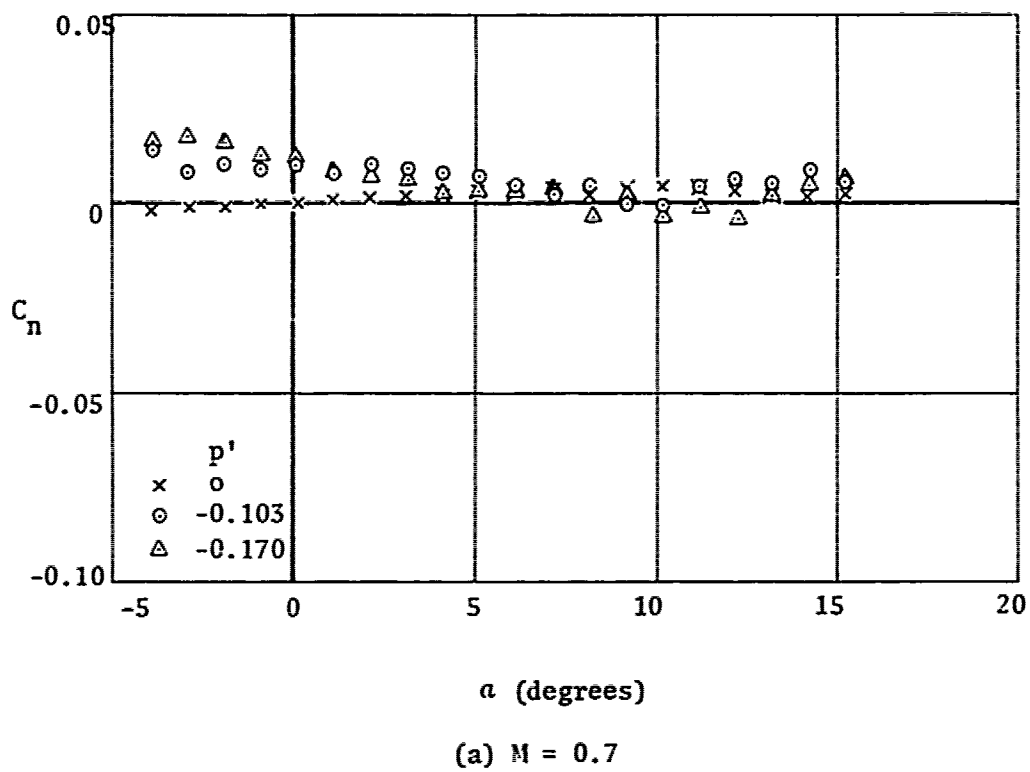


Figure 9. Variation of yawing moment coefficient with incidence, Mach no. and roll rate



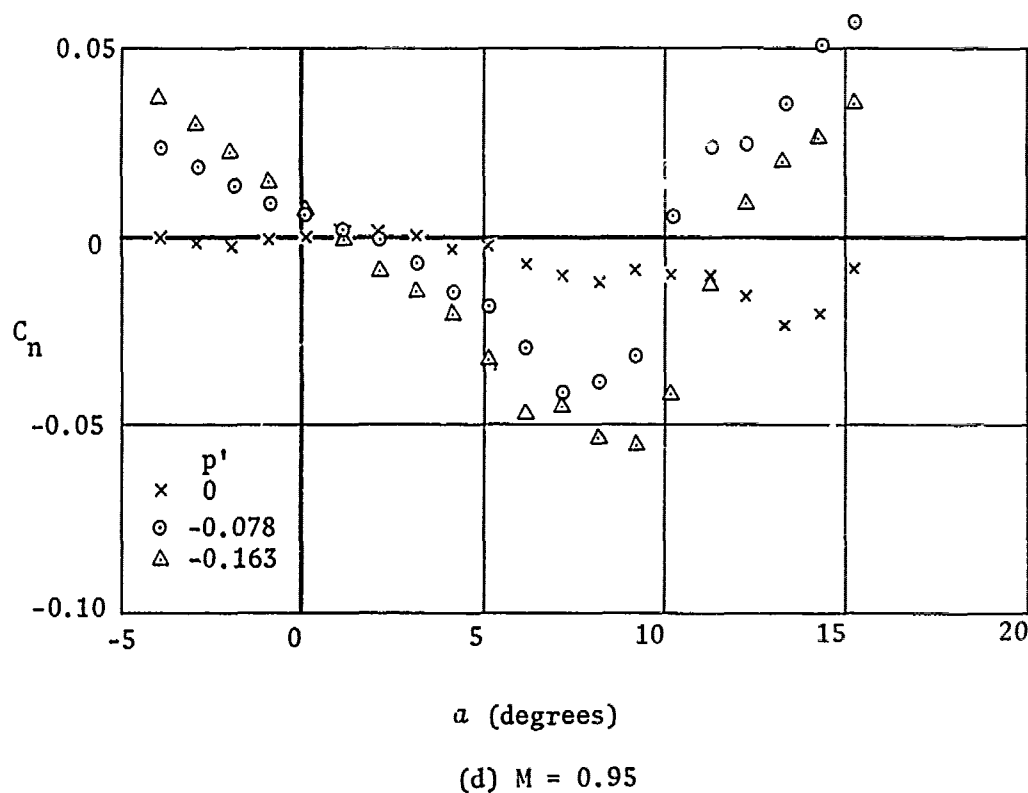
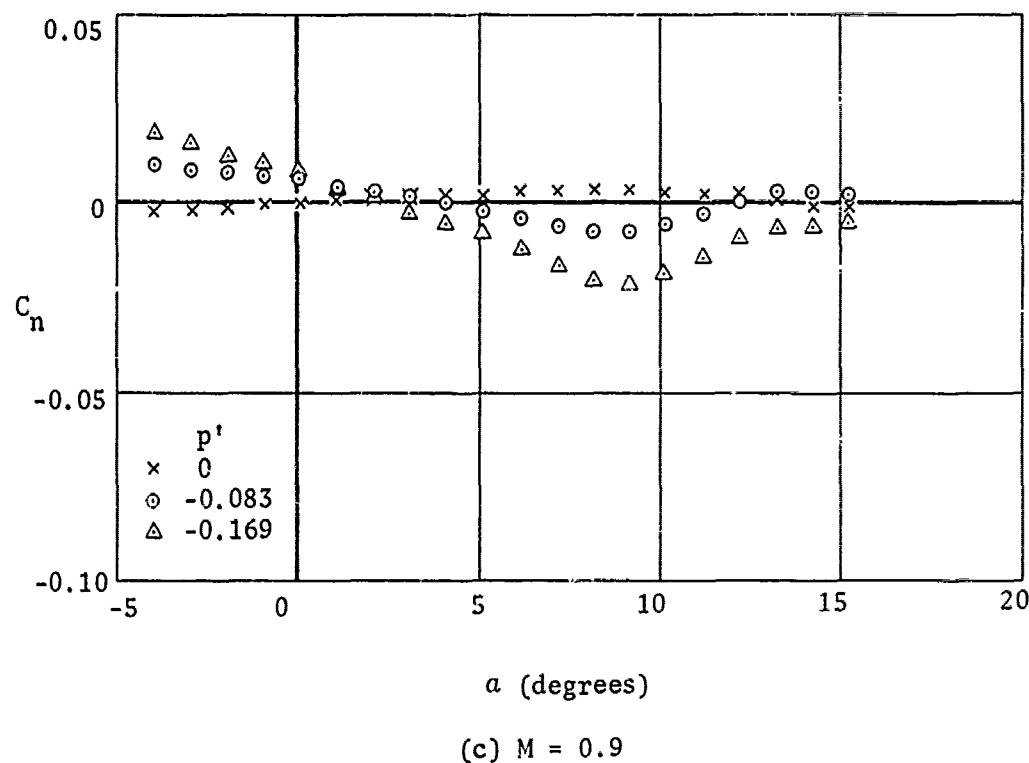
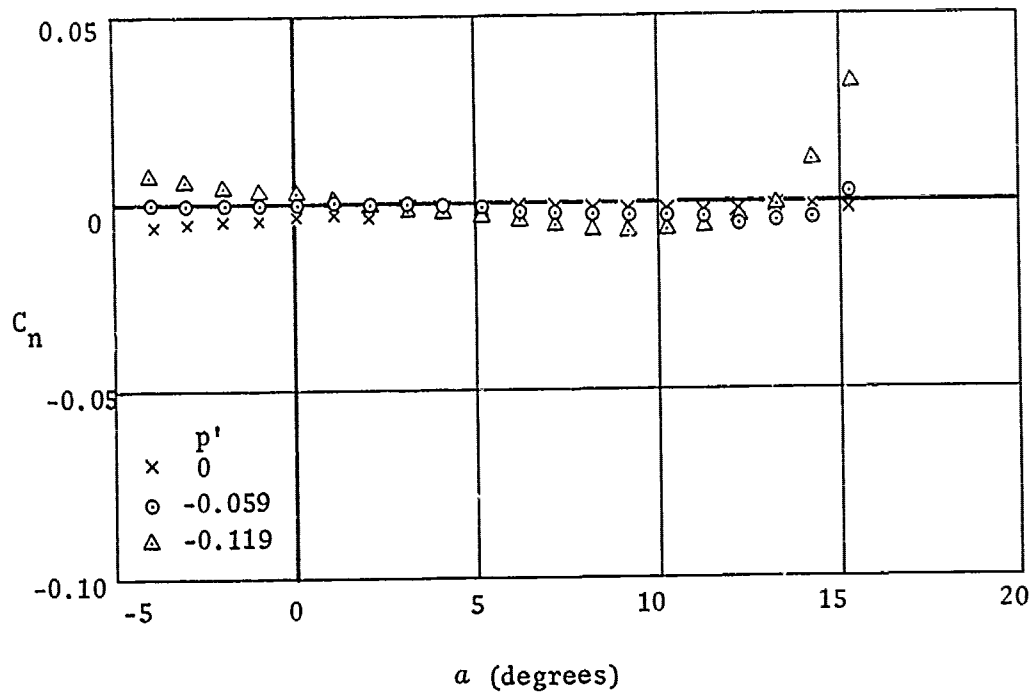


Figure 9(Contd.). Variation of yawing moment coefficient with incidence, Mach no. and roll rate



(e)  $M = 1.4$

Figure 9(Contd.). Variation of yawing moment coefficient with incidence, Mach no. and roll rate

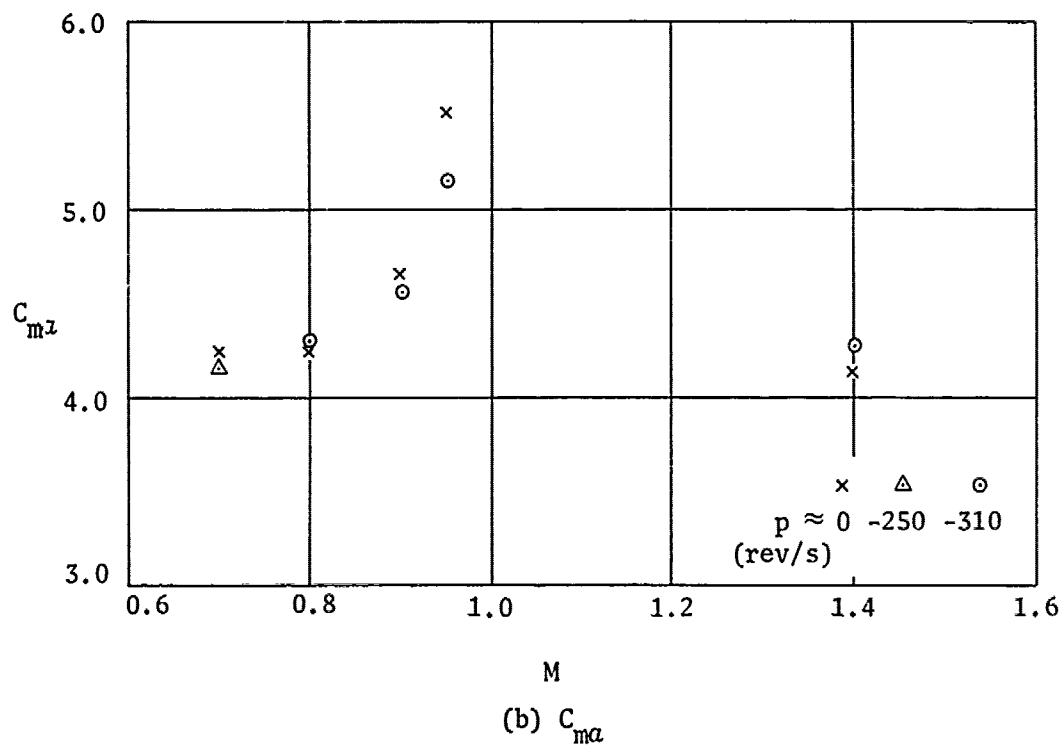
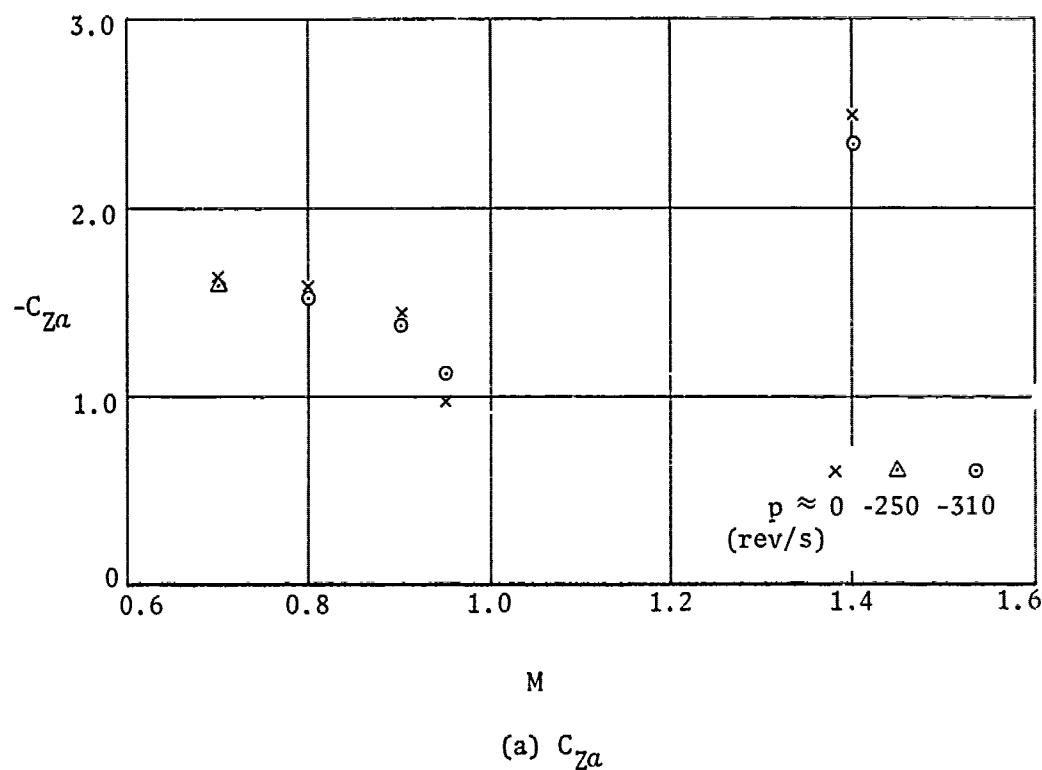


Figure 10. Variation of  $C_{Za}$ ,  $C_{ma}$ ,  $C_{Y_{pa}}$  and  $C_{n_{pa}}$  with Mach no. and roll rate, at  $\alpha = 0^\circ$

Figure 10(Contd.).

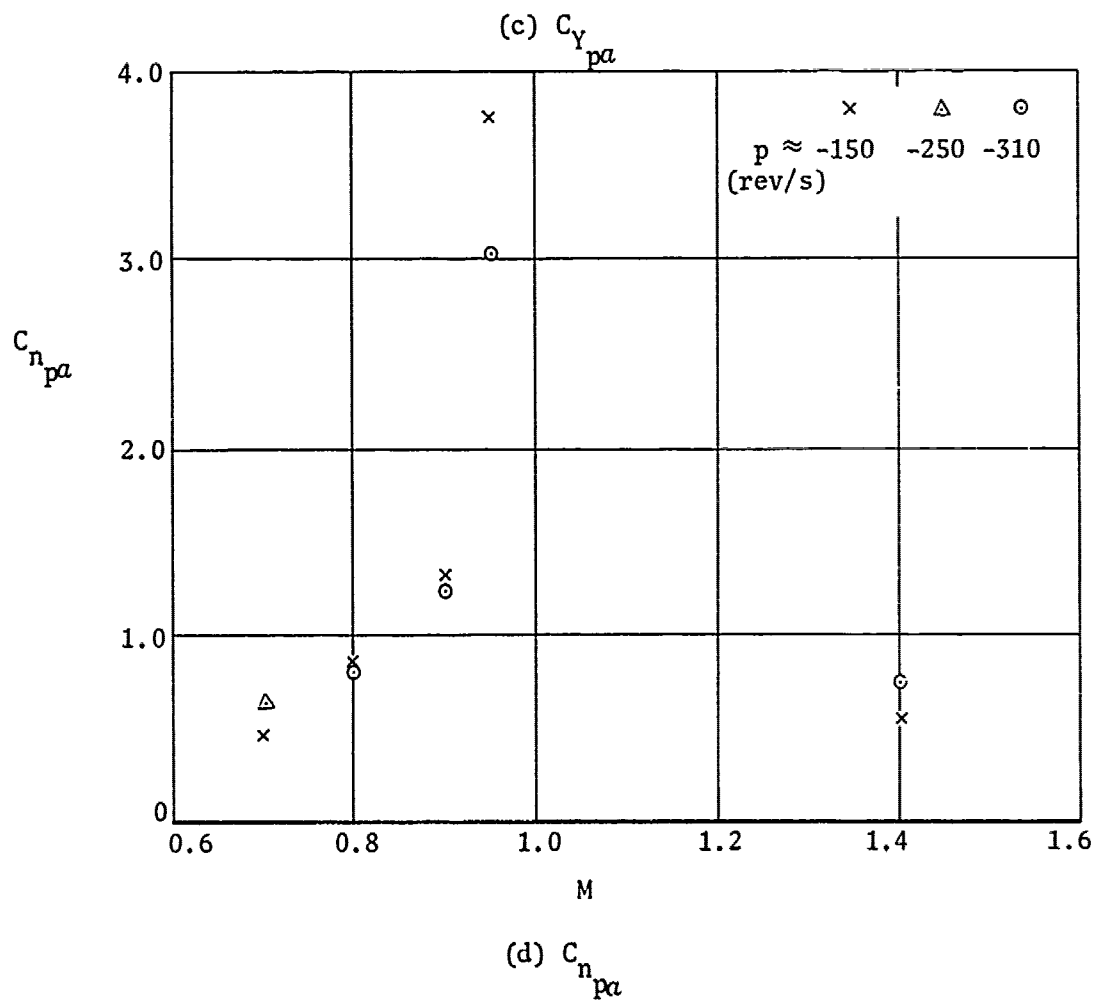
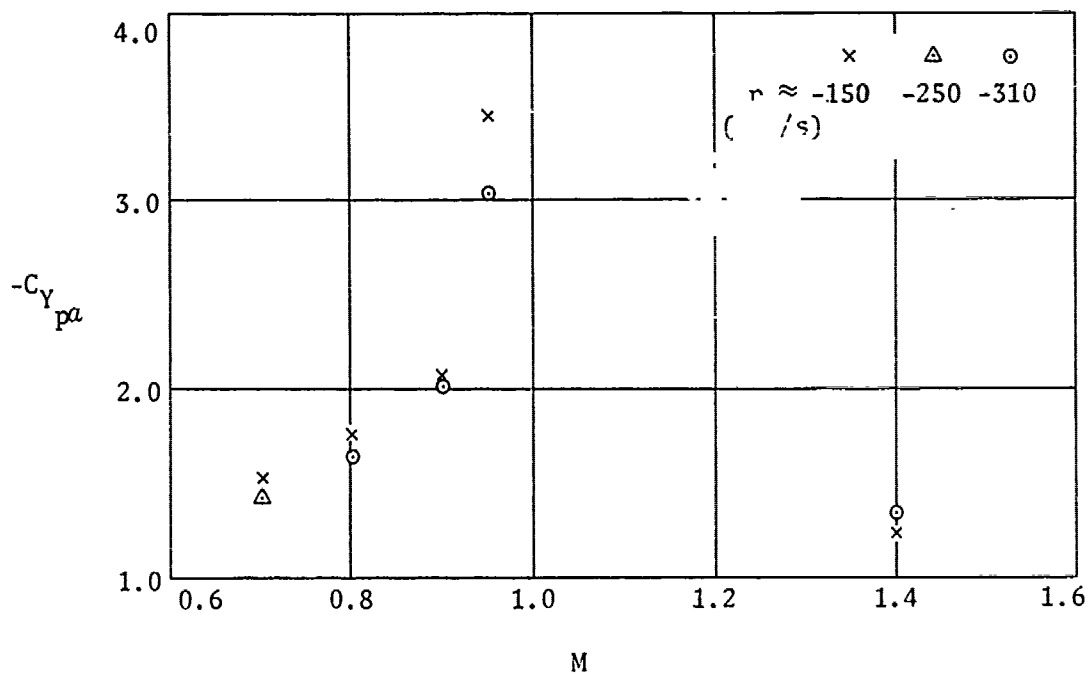


Figure 10(Contd.). Variation of  $C_{Za}$ ,  $C_{ma}$ ,  $C_{Y_{pa}}$  and  $C_{n_{pa}}$  with Mach no. and roll rate, at  $\alpha = 0^\circ$

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